

Rotation Damping in Stellarators

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Outline

1. Introduction
2. Fluid Equations
3. δf Code and Kinetic Equation
4. Damping Coefficient
5. Ambipolar Field

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Introduction

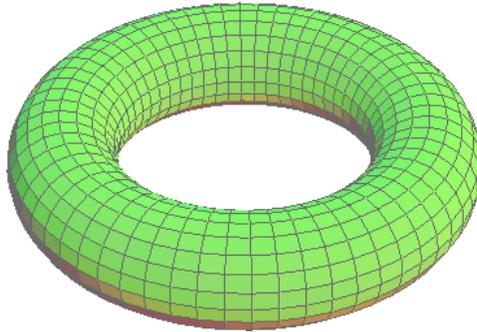
- *Importance of Rotation*
 - Transport barriers
 - Improved plasma performance
- *Prediction of Rotation Rate*
 - In toroidal symmetry:

$$\tau_{\phi} \rightarrow \tau_i \left(\frac{a}{\rho} \right)^2$$

(1)

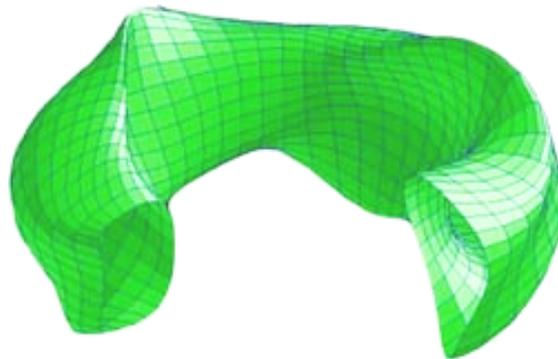
- In arbitrary stellarator, $\tau_{\phi} \rightarrow \tau_i$
- Use δf code to estimate the flow
- Momentum conserving operator causes difficulties

Symmetric



$$\frac{|\mathbf{B}|}{B_0} = 1 + \epsilon_{10} \cos(\theta)$$

Asymmetric



$$\frac{|\mathbf{B}|}{B_0} = 1 + \sum \epsilon_{mn} \cos(m\theta - n\phi)$$

Canonical toroidal momentum, L_ϕ no longer conserved

$$\vec{L} = \vec{p} + e\vec{A}$$

Fluid Equations

Force-Balance Equation:

$$\rho \frac{d\vec{u}}{dt} = -\vec{\nabla} \cdot \overset{\leftrightarrow}{\mathbf{P}} + en \left(\vec{E} + \vec{u} \times \mathbf{B} \right) + \vec{F}_d - \vec{R} \quad (2)$$

$\vec{F}_d \rightarrow$ applied force

$\vec{u} \rightarrow$ flow velocity of the fluid

$\overset{\leftrightarrow}{\mathbf{P}} \rightarrow$ pressure tensor, given by:

$$\overset{\leftrightarrow}{\mathbf{P}} = p_{\parallel} \hat{\mathbf{b}}\hat{\mathbf{b}} + p_{\perp} (\overset{\leftrightarrow}{\mathbf{I}} - \hat{\mathbf{b}}\hat{\mathbf{b}}) \quad (3)$$

- Want τ such that

$$m\vec{u} = \overset{\leftrightarrow}{\tau} \cdot \vec{F}_d \quad (4)$$

$$\mathbf{B} = \frac{1}{\mathcal{J}} \left(\frac{d\vec{x}}{d\phi} + \iota \frac{d\vec{x}}{d\theta} \right) = G\vec{\nabla}\phi + I\vec{\nabla}\theta + \beta_*\vec{\nabla}\psi \quad (5)$$

- \mathcal{J} is the Jacobian , $\mathcal{J} = \mu_o \frac{G+\iota I}{B^2}$
- Net applied toroidal torque is:

$$\mathcal{T}_\phi \equiv \oint \frac{\partial \vec{x}}{\partial \phi} \cdot \vec{F} \mathcal{J} d\theta d\phi \quad (6)$$

- $\vec{u} \times \mathbf{B}$ integral proportional to the net flow of charge across a surface

$$en \oint \vec{u} \times \mathbf{B} \cdot \frac{d\vec{x}}{d\phi} \mathcal{J} d\theta d\phi = en \oint \iota \vec{u} \cdot \vec{\nabla}\psi \mathcal{J} d\theta d\phi = \iota \frac{dQ}{dt}$$

Likewise, $en \oint \vec{u} \times \mathbf{B} \cdot \frac{d\vec{x}}{d\theta} \mathcal{J} d\theta d\phi = -\frac{dQ}{dt}$

- For the pressure tensor, after much algebra:

$$\oint \frac{d\vec{x}}{d\phi} \cdot \vec{\nabla} \cdot \vec{\mathbf{P}} \mathcal{J} d\theta d\phi = \oint \frac{1}{2} \frac{\partial (p_{\perp} + p_{\parallel})}{\partial \phi} \mathcal{J} d\theta d\phi \quad (7)$$

- Canonical Angular Momentum:

$$\vec{L} = \vec{p} + e\vec{A}, \quad \vec{A} = \psi \vec{\nabla} \theta - \psi_p \vec{\nabla} \phi$$

then,

$$\vec{L} \cdot \frac{d\vec{x}}{d\phi} = \rho \vec{u} \cdot \frac{\partial \vec{x}}{\partial \phi} - e\psi_p,$$

- Surface integral of ϕ component:

$$\frac{d\mathcal{L}_{\phi}}{dt} \equiv \oint \rho \frac{d\vec{u}}{dt} \cdot \frac{\partial \vec{x}}{\partial \phi} \mathcal{J} d\theta d\phi - \iota \frac{dQ_c}{dt} \quad (8)$$

- ϕ component of the fluid equation is then:

$$\frac{d\mathcal{L}_{\phi}}{dt} = \mathcal{T}_{\phi} - \oint \frac{1}{2} \frac{\partial (p_{\perp} + p_{\parallel})}{\partial \phi} \mathcal{J} d\theta d\phi \quad (9)$$

The δf method

- The Fokker-Planck equation,

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \vec{v} \cdot \frac{\partial f}{\partial \vec{x}} + \frac{q}{m} \left(\vec{E} + \vec{v} \times \mathbf{B} \right) \cdot \frac{\partial f}{\partial \vec{v}} = C(f) \quad (10)$$

- Assume the distribution function, f , is approximately a Maxwellian.

$$f = F_m (1 + \delta) \quad (11)$$

- The Maxwellian has the form

$$F_m (\psi, H) = \exp [\zeta (\psi) - 1 - H\beta (\psi)] \quad (12)$$

- The Hamiltonian, H , is

$$H = \frac{(2\pi)^2}{2m} \left(\frac{B}{\mu_o G} \right)^2 \left(p_\phi + \frac{q\psi_p}{2\pi} \right)^2 + \mu B \quad (13)$$

- Fokker Planck Equation:

$$\frac{d\delta}{dt} + \vec{v}_g \cdot \vec{\nabla} \psi \frac{\partial \ln F_m}{\partial \psi} + \vec{F}_d \cdot \frac{\partial F_m}{\partial \vec{v}} = C_m(\delta) \quad (14)$$

- Applied forces

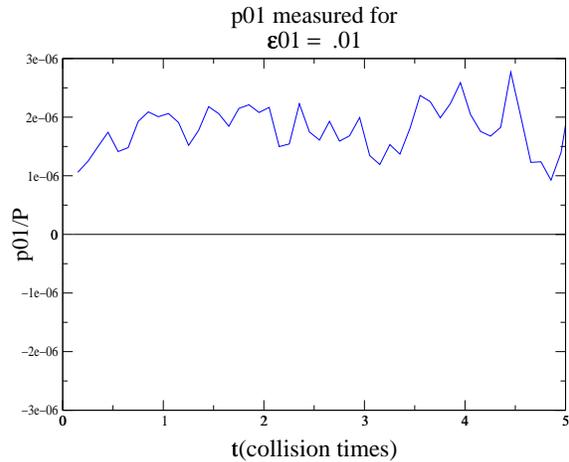
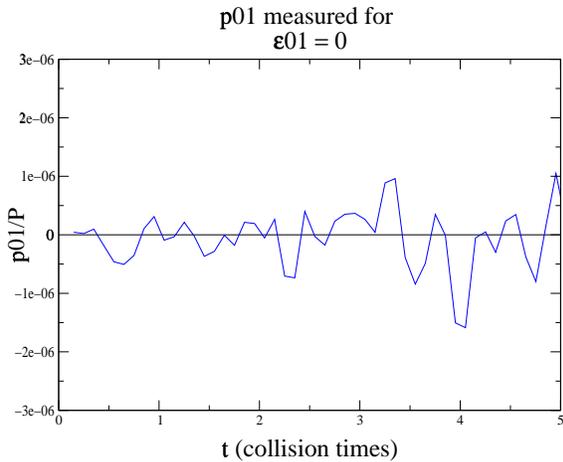
$$\vec{F}_d = -q \frac{d\Phi}{d\psi} \vec{\nabla} \psi + f_\phi \vec{\nabla} \phi + f_\theta \vec{\nabla} \theta \quad (15)$$

- During each time-step
 - Hamiltonian step
 - &
 - Collision step
- Particles are restricted to narrow ψ -annulus

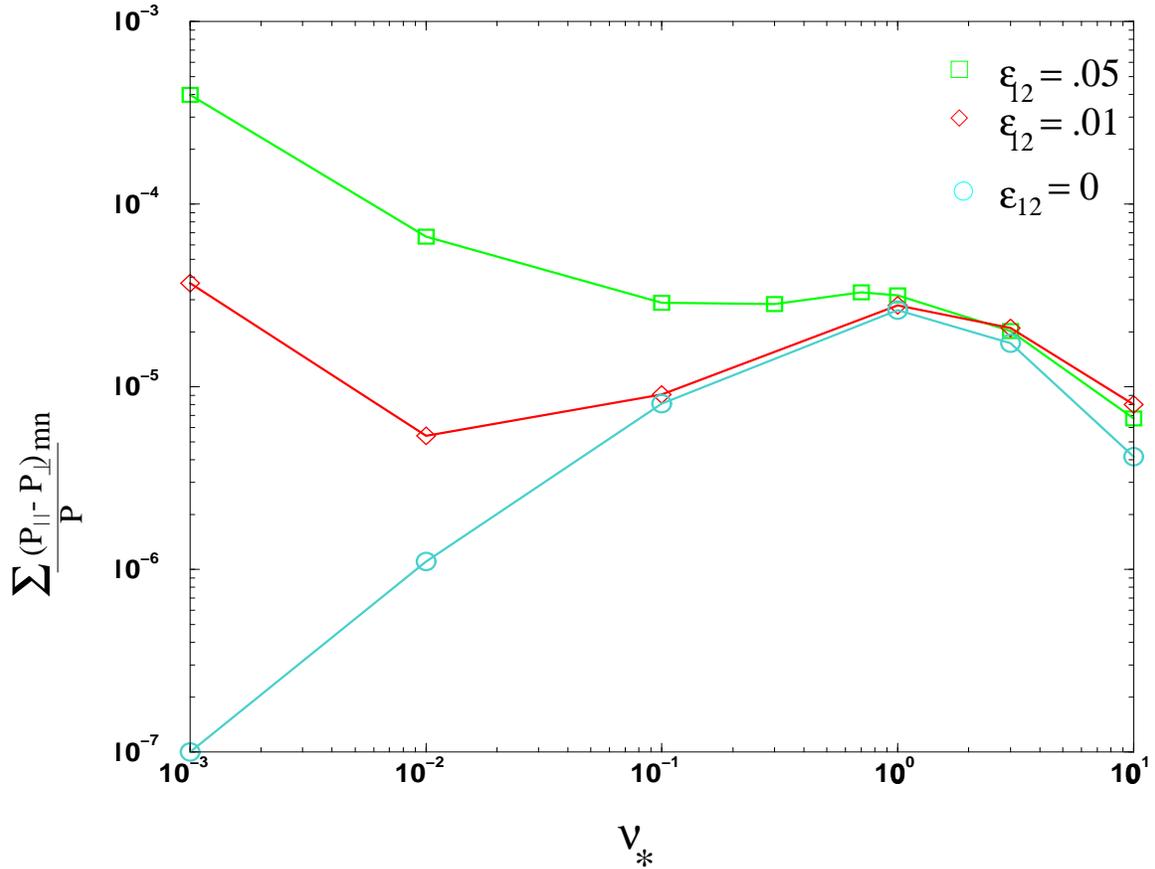
- Calculation using δ'_i 's

$$p_{\perp} = \sum_{m,n} (p_{\perp})_{m,n} e^{2\pi i(n\phi - m\theta)} \quad (16)$$

$$\begin{aligned} (p_{\perp})_{mn} &= \int \frac{1}{2} m v_{\perp}^2 f e^{-2\pi i(n\phi - m\theta)} d^3 v d\theta d\phi \\ &= \frac{m v_0^2 \frac{dn}{d\psi} \sum_i [(1 - \lambda_i^2) \delta_i B_i^2 e^{-2\pi i(n\phi_i - m\theta_i)}]}{2 \sum_i B_i^2} \end{aligned}$$



Viscosity calculation with δf code:



Analytic prediction at high collisionality:

$$(P_{||} - P_{\perp}) \approx \frac{3}{2} \frac{nT}{\nu} \left[\hat{\mathbf{b}} \cdot \vec{\nabla} (\hat{\mathbf{b}} \cdot \vec{v}) - (\hat{\mathbf{b}} \cdot \vec{\nabla} \hat{\mathbf{b}}) \cdot \vec{v} \right] \quad (17)$$

(Grimm and Johnson, Plasma Phys. 14, 615(1972))

- The viscosity is linearly related to $\delta'_i s$.
- $\delta_i \propto F_d$ from Fokker-Planck
- Therefore, $p_{\perp} \propto F_d, p_{\parallel} \propto F_d$

$$\oint \frac{1}{2} \frac{\partial (p_{\perp} + p_{\parallel})}{\partial \phi} \mathcal{J} d\theta d\phi = \beta_{\phi}^{(\phi)} f_{\phi} + \beta_{\theta}^{(\phi)} f_{\theta} + \beta_{\psi}^{(\phi)} \frac{d\Phi}{d\psi}$$

$$\oint \frac{1}{2} \frac{\partial (p_{\perp} + p_{\parallel})}{\partial \theta} \mathcal{J} d\theta d\phi = \beta_{\phi}^{(\theta)} f_{\phi} + \beta_{\theta}^{(\theta)} f_{\theta} + \beta_{\psi}^{(\theta)} \frac{d\Phi}{d\psi}$$

- All β' 's can be calculated with a single simulation
- Hamiltonian only calculated once

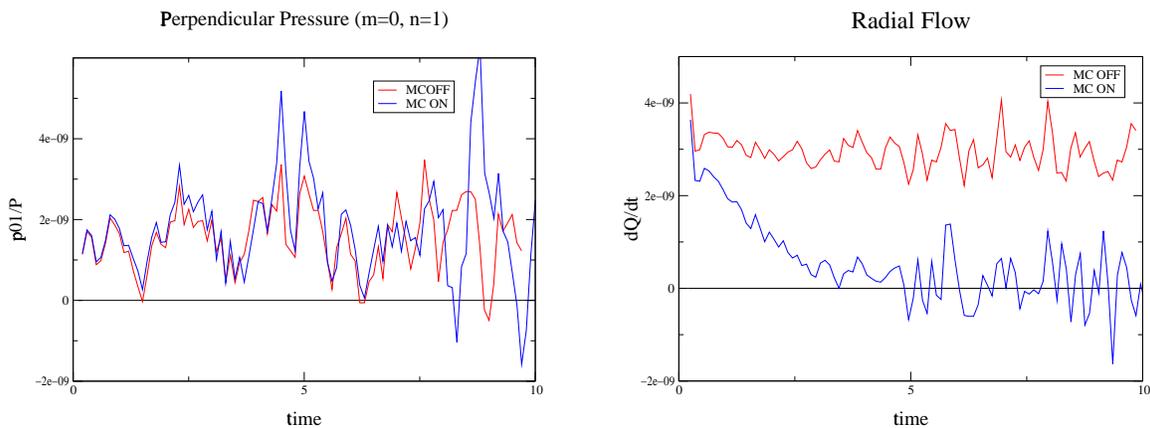
Momentum Conservation

- Modified Lorentz collision operator that conserves momentum:

$$C(f) = \frac{\nu}{2} \frac{\partial}{\partial \lambda} \left[(1 - \lambda^2) \frac{\partial f}{\partial \lambda} \right]$$

$$\rightarrow \frac{\nu}{2} \frac{\partial}{\partial \lambda} \left[(1 - \lambda^2) \left(\frac{\partial f}{\partial \lambda} - 3 \frac{u_{\parallel}}{v} f \right) \right] \quad (18)$$

- $\lambda \equiv \frac{v_{\parallel}}{v}$
- u_{\parallel} in Eq. 18 is averaged over a collision time
- Imperfect momentum conservation has greater effect on $\frac{dQ}{dt}$ than p_{\perp}



- In the δf code:

$$\frac{d\delta}{dt} = -\vec{v}_g \cdot \vec{\nabla}\psi \frac{\partial \ln F_m}{\partial \psi} - \frac{m}{T} \vec{F}_d \cdot \vec{v}_g + 2\nu (1 - 3\lambda^2) \langle \lambda \rangle \quad (19)$$

- In principle, $\langle \lambda \rangle \equiv \int \lambda \delta d\lambda$.

- Let

$$\langle \lambda \rangle \equiv \int \lambda \delta d\lambda + \frac{\Lambda_{\parallel}}{\oint \mathcal{J} d\theta d\phi} \quad (20)$$

- Acts as additional driving term:

$$\oint \frac{1}{2} \frac{\partial (p_{\perp} + p_{\parallel})}{\partial \phi} \mathcal{J} d\theta d\phi = \beta_{\phi}^{(\phi)} f_{\phi} + \beta_{\theta}^{(\phi)} f_{\theta} + \beta_{\psi}^{(\phi)} \frac{d\Phi}{d\psi} + \beta_{\Lambda}^{(\phi)} \Lambda_{\parallel} \quad (21)$$

- Now have two Eqns., (θ, ϕ components of the fluid equation), and two unknowns $\left(\Lambda_{\parallel}, \frac{d\Phi}{d\psi} \right)$

Damping Coefficient

- Have

$$\frac{d\Phi}{d\psi} = \delta \vec{E} \cdot \frac{d\vec{x}}{d\psi} \propto F_d$$

- Therefore

$$\delta \vec{u}_{\perp} = \frac{\delta \vec{E} \times \mathbf{B}}{B^2} \quad (22)$$

- Need perturbed parallel flow, $u_{\parallel} = u_{\parallel o} + \delta u_{\parallel}$

$$\delta u_{\parallel} = \gamma_{\phi} f_{\phi} + \gamma_{\theta} f_{\theta} + \gamma_{\psi} \frac{d\Phi}{d\psi} \quad (23)$$

- Therefore:

$$m\vec{u} = \overleftrightarrow{\tau} \cdot \vec{F}_d \quad (24)$$

Ambipolarity

- Can also use δf code to find radial ambipolar field.

$$j_r = en [(u_i)_r - (u_e)_r] = \sigma (E_r - E_a) \quad (25)$$

- Background ambipolar field in the orbit equations
- Adding driving forces, requires additional field
- Separate the perturbed field

$$j_r = \sigma ((E_r - E_a)_0 + (\delta E_r - \delta E_a)) \quad (26)$$

- The perpendicular conductivity is

$$\sigma = \frac{\beta_\psi^{(\phi)} \beta_\Lambda^{(\theta)} - \beta_\psi^{(\theta)} \beta_\Lambda^{(\phi)}}{\beta_\Lambda^{(\phi)} + \iota \beta_\Lambda^{(\theta)}} \quad (27)$$

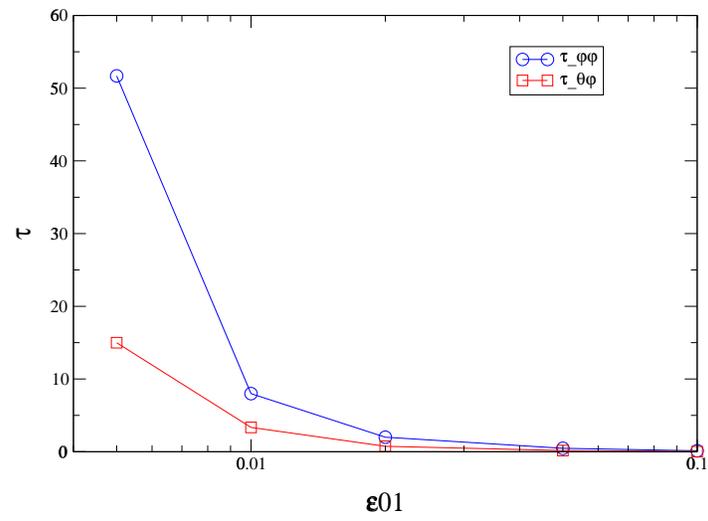
- If momentum conservation were perfect:

$$\sigma = \frac{1}{\iota} \beta_\psi^{(\phi)} = -\beta_\psi^{(\theta)}$$

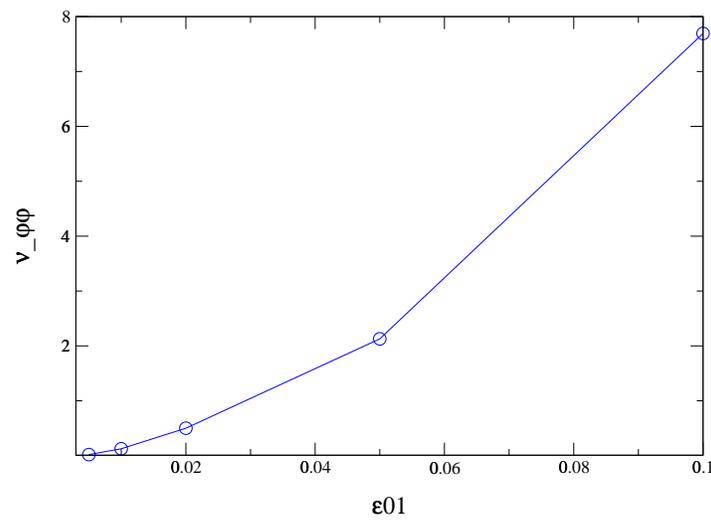
Calculations

- Found $\tau \propto \left(\frac{1}{\epsilon_{01}}\right)^2$

Damping time



Damping Coefficient



Summary

- Fluid eqns. improve δf calculations of rotation damping
- Accounted for problems with collision operator in δf
- Used δf and fluid eqns. to find damping coefficient and perturbed $\frac{dQ}{dt}$
- Demonstrated $\sim \frac{1}{\delta^2}$ dependence of τ