

Ballooning modes in quasi-symmetric devices: Effects of breaking symmetry

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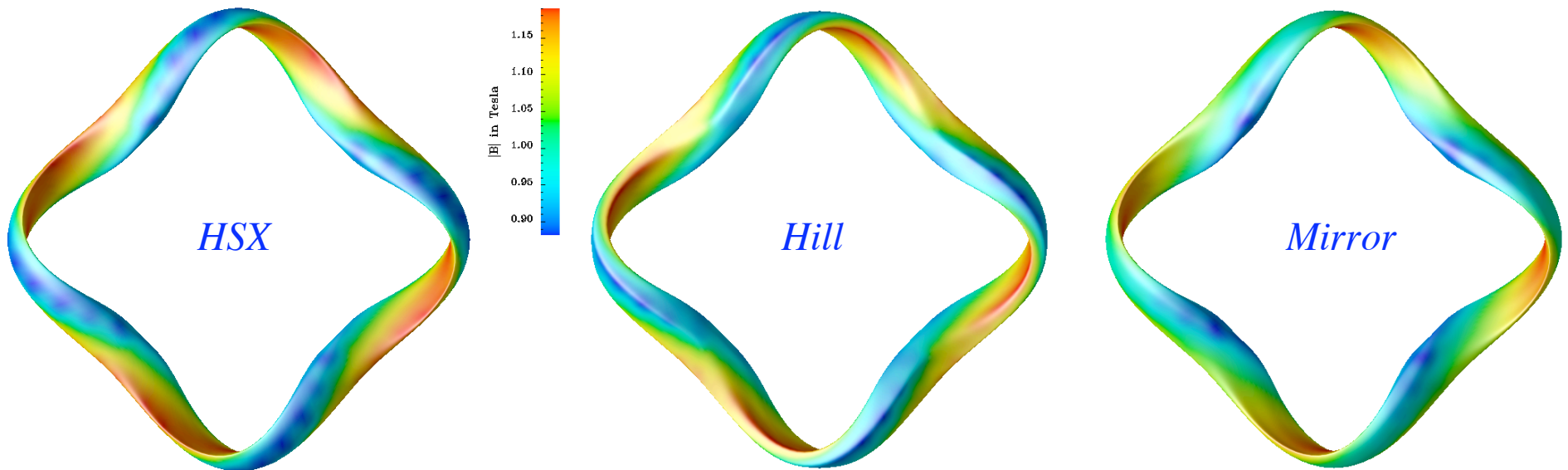
Overview



- Breaking symmetry:
 - For HSX, 3 different equilibria
 - * *Standard, quasi-helically symmetric case*
 - * *Mirror case*
 - * *Hill case*
 - For QPS use a range of currents in the *TF* coils to modify the quasi-poloidal symmetry
- Examine the impact of symmetry breaking on ballooning stability
 - Effect on local shear and curvature
 - Ballooning results from COBRAVMEC

HSX has tested configurations that break its designed quasi-symmetry

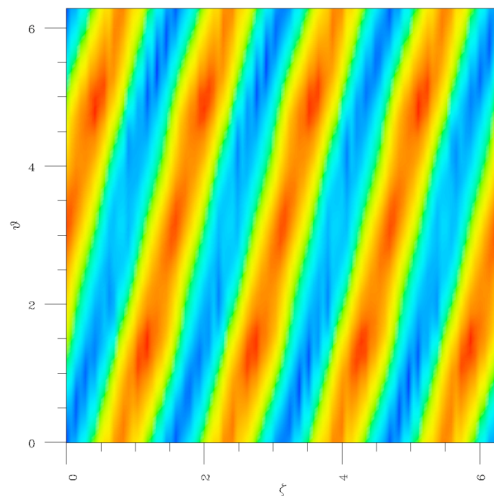
- We have examined three different HSX cases:
 - *HSX*: standard, quasi-helically symmetric case
 - *Mirror*: adds a mirror term to break the symmetry
 - *Hill*: adds a hill to negatively impact stability



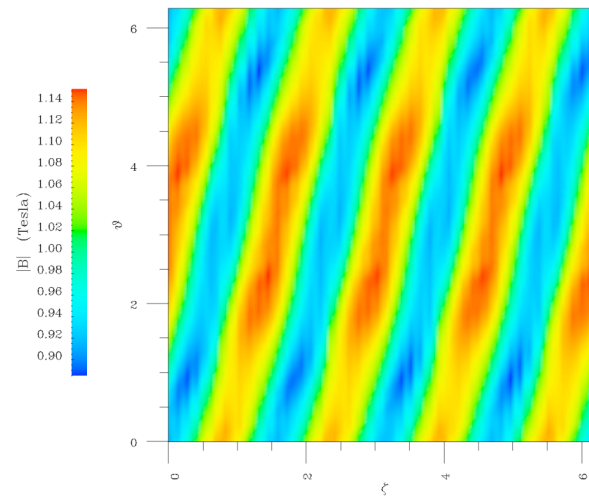
Both the *Hill* and *Mirror* cases have reduced quasi-symmetry



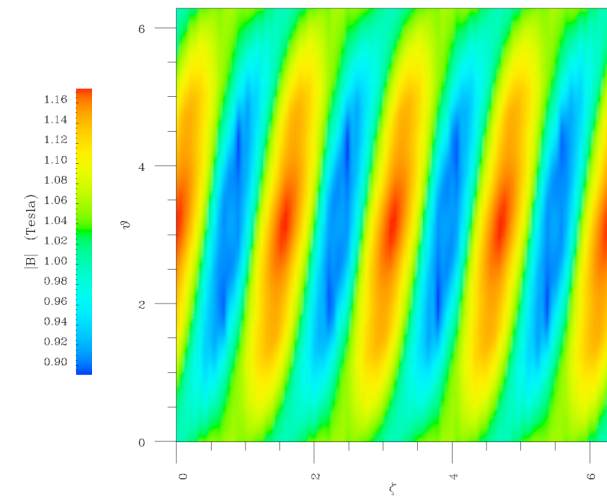
- Contour plots of $|B|$ in Boozer coordinates on the $S = 0.8182$ surface for all three cases
 - The reduced quasi-symmetry is noticeably visible



HSX



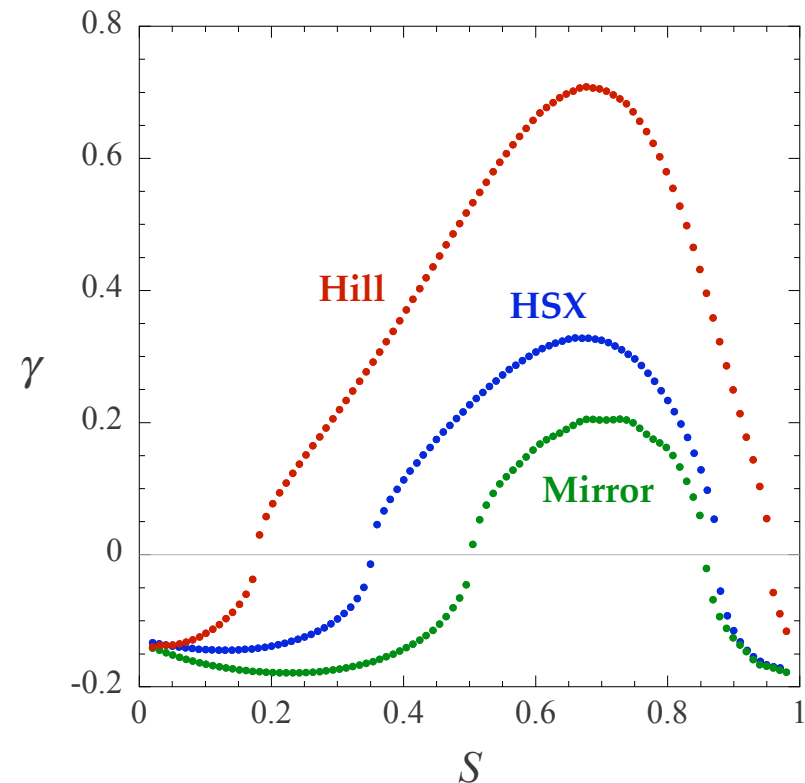
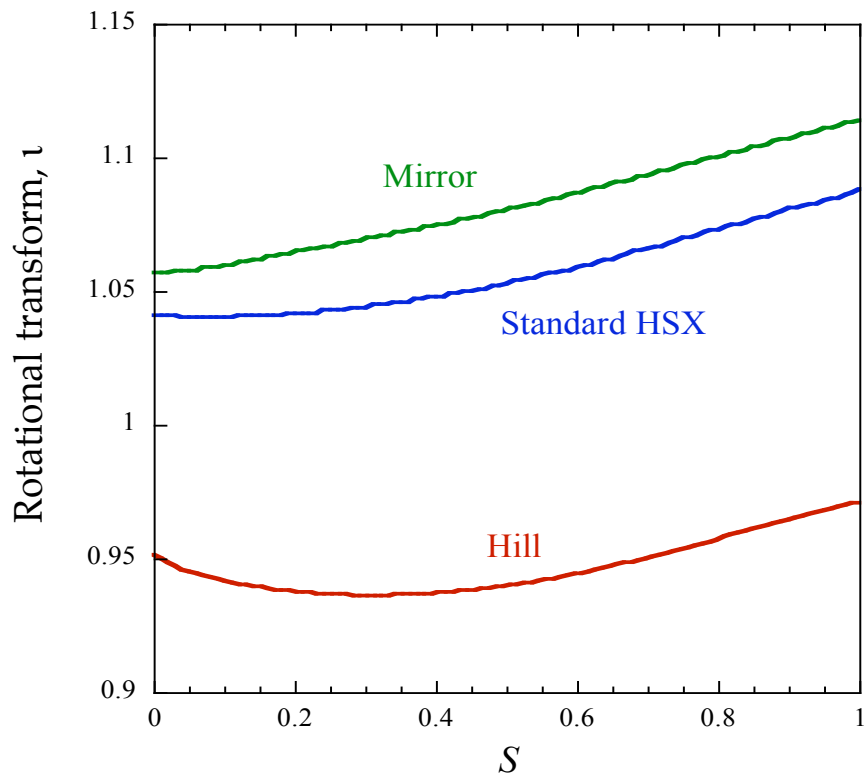
Hill



Mirror

The HSX cases have a wide range of equilibrium and stability properties

- Rotational transform profiles and ballooning growth rates ($\theta_k = 0, \alpha = 0$) at $\beta = 2.35\%$, $|B| = 1$ T, for each HSX case



Solving the ballooning eigenvalue equation in VMEC coordinates



- We use COBRAVMEC to solve the ideal MHD ballooning equation
 - Given a VMEC equilibrium (wout file), COBRAVMEC obtains the MHD eigenvalue as a function of the normalized flux, S , the field line label, $\alpha = q\theta - \zeta$, and the ballooning parameter, $\theta_k = k_q/k_\alpha$.

$$(\vec{B} \cdot \nabla) \left[\frac{|\nabla \alpha|^2}{B^2} (\vec{B} \cdot \nabla) \right] F + \left(\frac{R_0}{a} \right)^2 \frac{\beta_0 p'}{\Psi'^2} \kappa_s F + \lambda \frac{|\nabla \alpha|^2}{B^2} F = 0$$

- To obtain: $\lambda = \lambda(S, \alpha, \theta_k)$

Solving the ballooning eigenvalue equation in VMEC coordinates (cont.)



- The curvature that appears in the ballooning equation depends on both the VMEC normal and geodesic curvatures [see R. Sanchez, S. P. Hirshman, and H. V. Wong, *Computer Physics Communications* **135**, 82 (2001) for details]

$$\kappa_s = \kappa_{s_V} + \kappa_{\theta_V} \left(\frac{l' \zeta_V - \partial \lambda_V / \partial s_V}{1 + \partial \lambda_V / \partial \theta_V} \right)$$

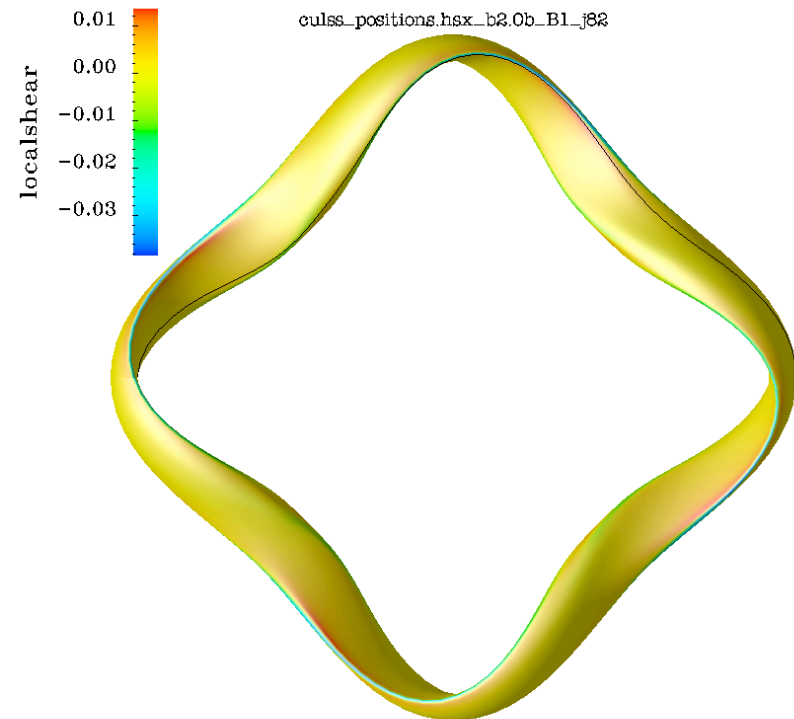
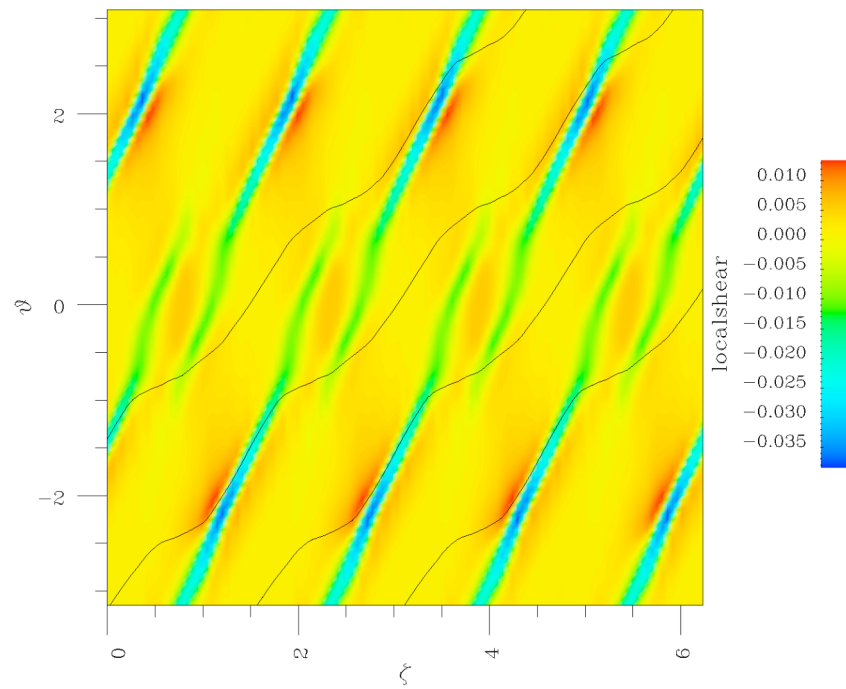
- Where the terms with subscript V refer to VMEC coordinates and λ_V is the VMEC lambda
- We will plot the normal curvature, κ_{s_V} , and the geodesic curvature, κ_{θ_V} , in VMEC coordinates

The local shear in HSX is small except near the narrow portions of the configuration



- Local shear for the standard HSX case on the $S = 0.8182$ surface, plane view and 3-D view

localshear in VMEC coordinates for culss_data.hsx_b2.0b_B1_j82 at $S=0.8182$

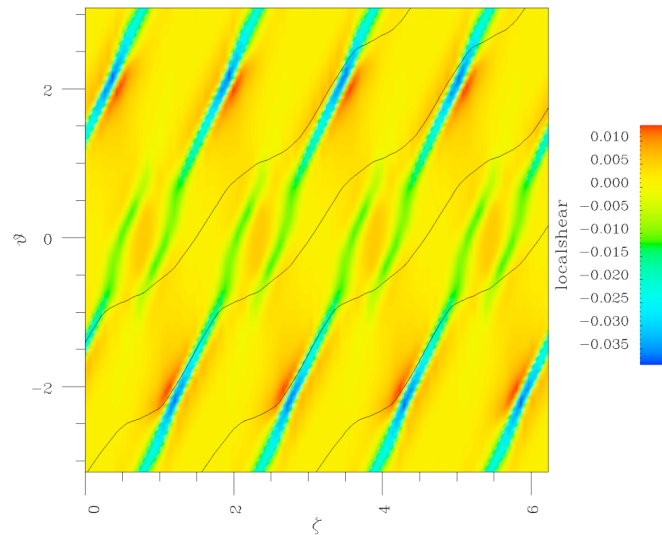


The local shear is similar in all three HSX configurations



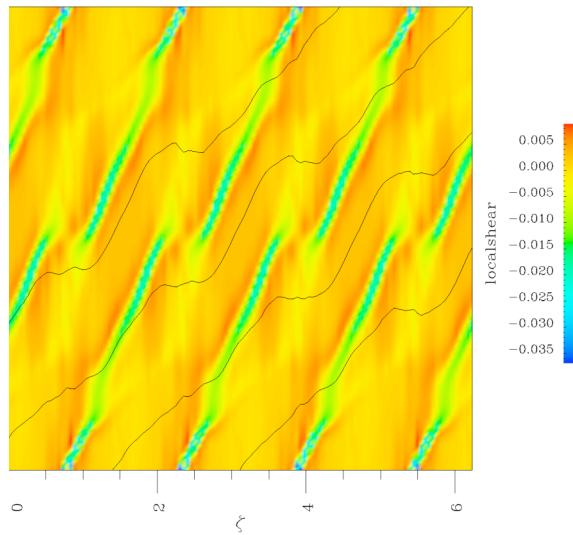
- Local shear on the $S = 0.8182$ surface, plane view, for the standard HSX, Hill and Mirror cases

localshear in VMEC coordinates for culss_data.hsx_b2.0b_B1_j82 at S=0.8182



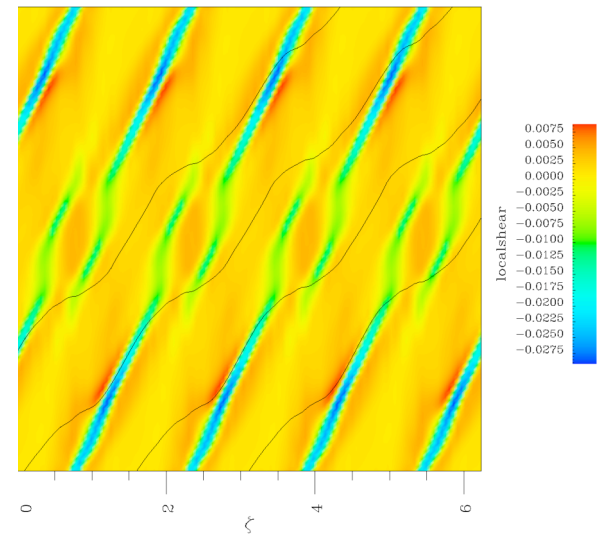
HSX

ar in VMEC coordinates for culss_data.hsx037hill_j82 at S=0.818



Hill

in VMEC coordinates for culss_data.hsx037mirror_j82 at S=0.8182



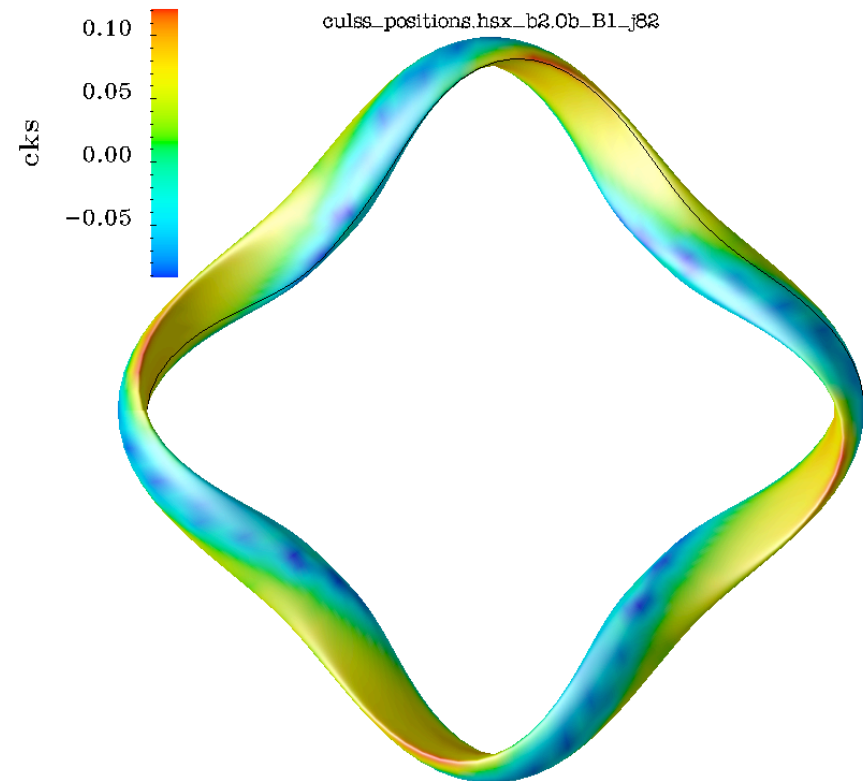
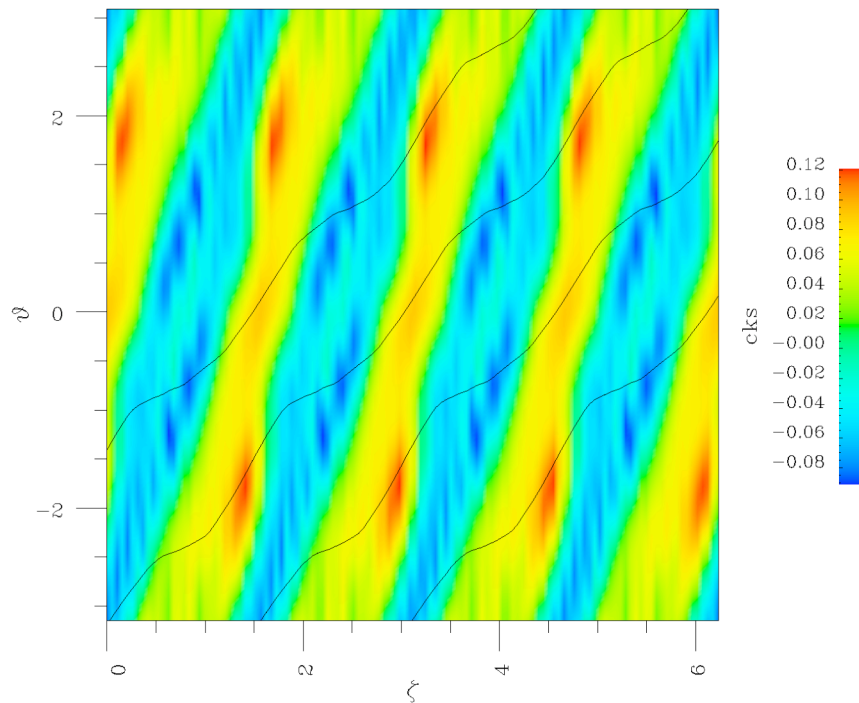
Mirror

Normal curvature in the standard HSX



- Normal curvature for the standard HSX case on the $S = 0.8182$ surface, plane view and 3-D view

cks in VMEC coordinates for culss_data.hsx_b2.0b_B1_j82 at $S=0.8182$

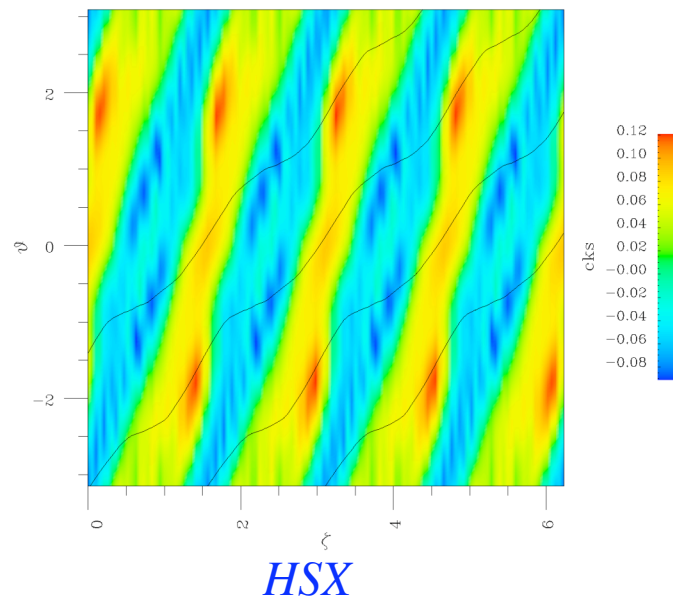


The normal curvature is different across the three configurations

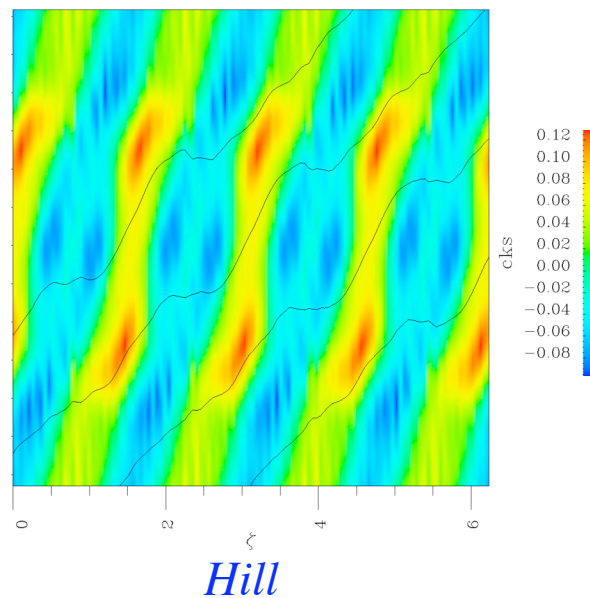


- Normal curvature on the $S = 0.8182$ surface, plane view, for the standard HSX, Hill and Mirror cases

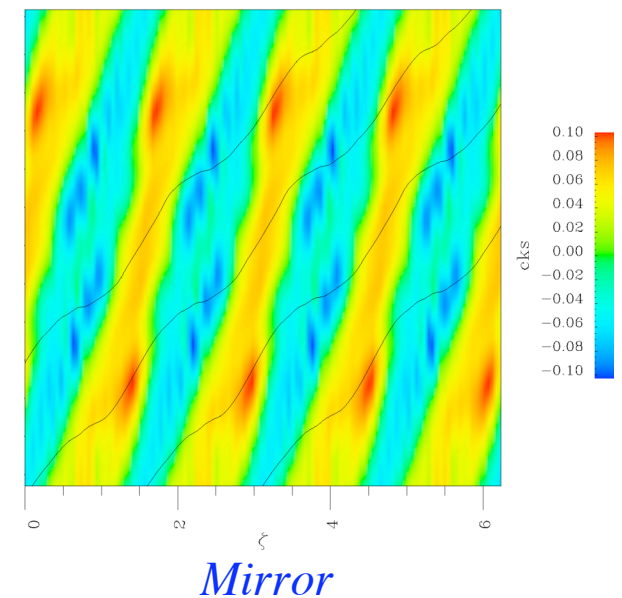
cks in VMEC coordinates for culss_data.hsx_b2.0b_B1_j82 at $S=0.8182$



MEC coordinates for culss_data.hsx037hill_j82 at $S=0.8182$



MEC coordinates for culss_data.hsx037mirror_j82 at $S=0.8182$

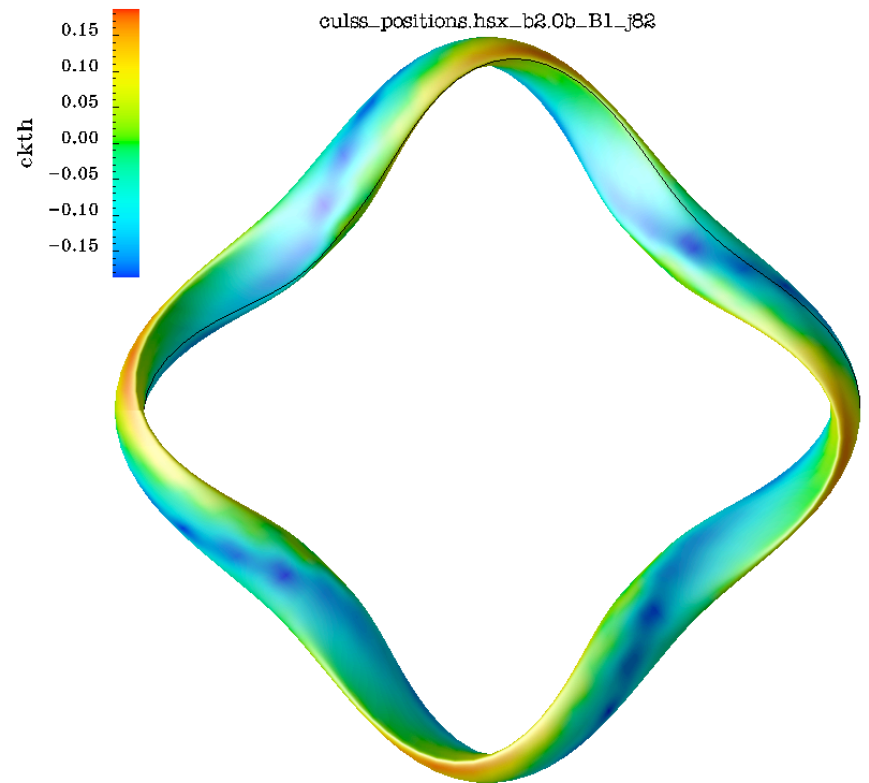
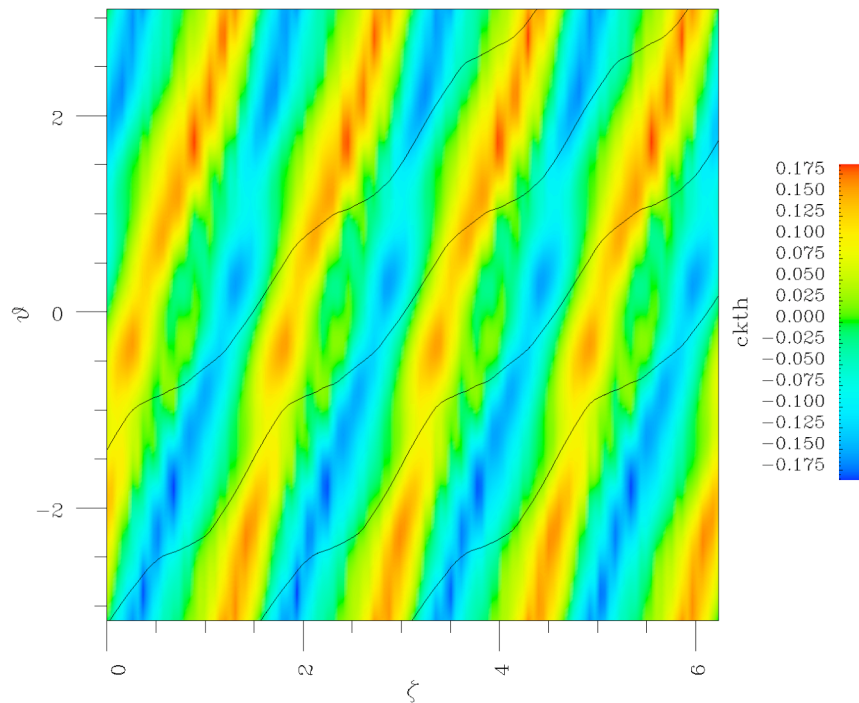


Geodesic curvature in the standard HSX



- Geodesic curvature for the standard HSX case on the $S = 0.8182$ surface, plane view and 3-D view

ckth in VMEC coordinates for culss_data.hsx_b2.0b_B1_j82 at $S=0.818$:

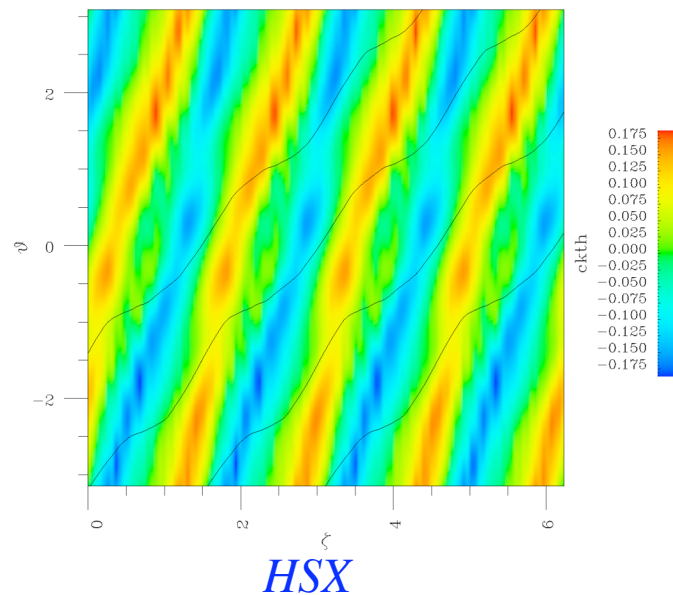


The geodesic curvature is very different for the *Hill* configuration

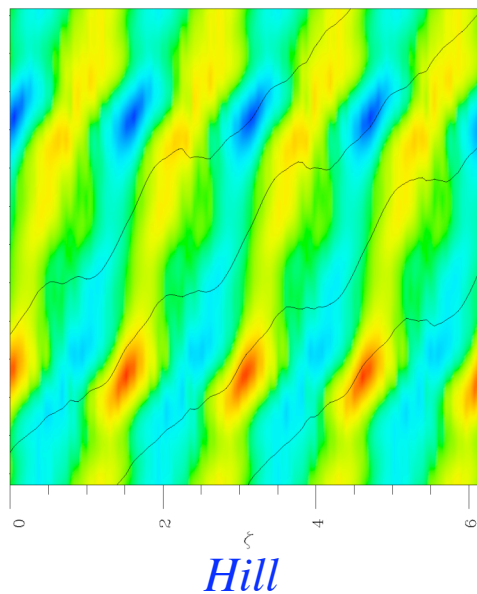


- Geodesic curvature on the $S = 0.8182$ surface, plane view, for the standard HSX, Hill and Mirror cases

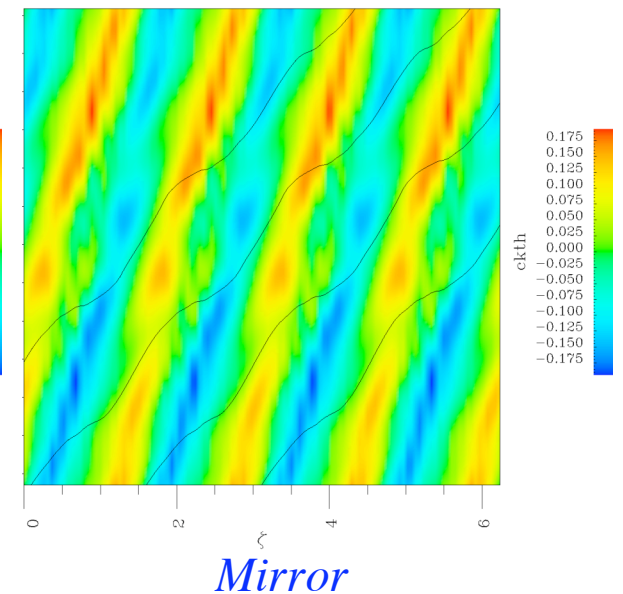
ckth in VMEC coordinates for culss_data.hsx_b2.0b_B1_j82 at $S=0.818$.



VMEC coordinates for culss_data.hsx037hill_j82 at $S=0.8182$



VMEC coordinates for culss_data.hsx037mirror_j82 at $S=0.818$.



The Ray Equations



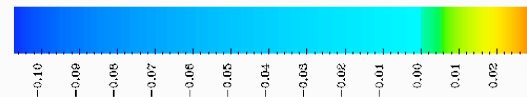
- Dewar and Glassers ray tracing theory can be used to obtain information about the global eigenmodes

$$\lambda = \lambda(q, \alpha, \theta_k)$$

$$\dot{q} = \frac{\partial \lambda}{\partial k_q}, \quad \dot{\alpha} = \frac{\partial \lambda}{\partial k_\alpha}, \quad \dot{k}_q = -\frac{\partial \lambda}{\partial q}, \quad \dot{k}_\alpha = -\frac{\partial \lambda}{\partial \alpha}$$

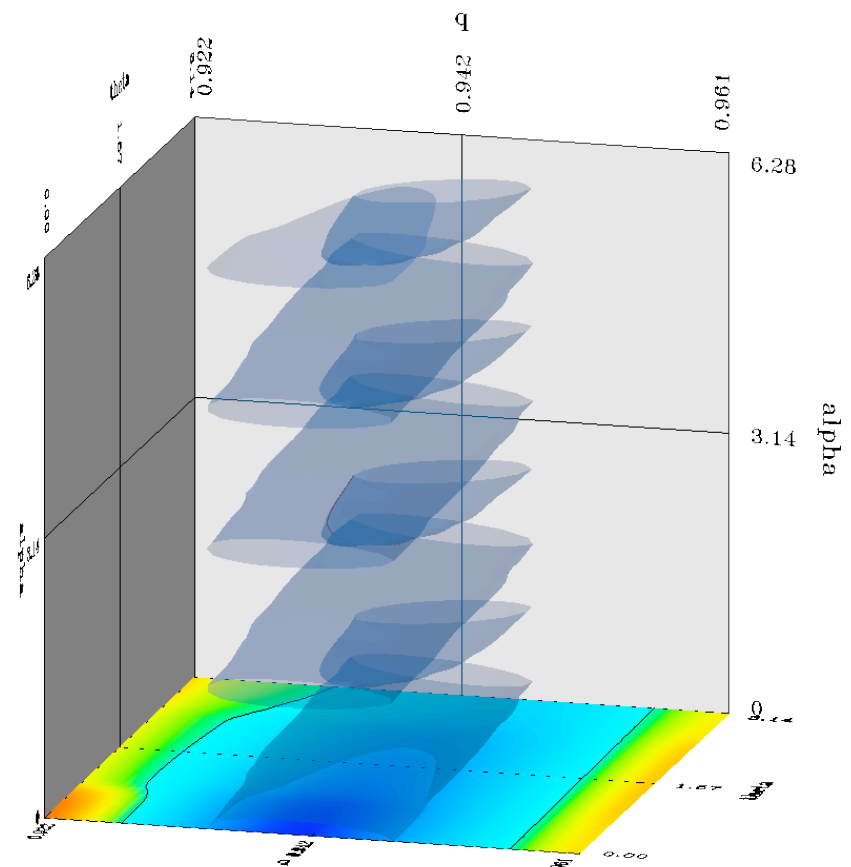
- Using the values of λ on a 45x45x91 grid in (q, θ_k, α) , we integrate the ray equations
 - Range for θ_k is 0 to π and for α is 0 to 2π

Ray tracing of ballooning modes in the standard HSX configuration

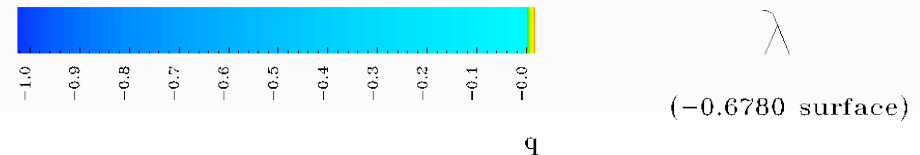


λ
(-0.0714 surface)

- Constant λ surfaces for the standard *HSX* case
 - $\beta = 2.35\%$
 - Surfaces of constant λ are localized in S , less localized in α , and extended in θ_k
 - The lack of dependence on θ_k makes tracing rays on these surfaces a challenge
 - Note: $S = 0.8182$, corresponds to the $q = 0.9302$ surface



Ray tracing of ballooning modes in the Hill configuration



(-0.6780 surface)

- Constant λ surfaces for the *Hill* case
 - $\beta = 2.9\%$
 - Similar to the standard HSX
 - Stronger dependence on θ_k
 - Note: $S = 0.8182$, corresponds to the $q = 1.043$ surface

