

# Modular Coil Interface Hardware C-C Inboard Shims PDR

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- Are the requirements defined? What is the proposed design?
- What is the status of mockup / access studies?
- Is the analysis consistent with proposed design?
- Have prior design review chits been addressed?
- Have all technical, cost, schedule, and safety risks been addressed?







Requirements are derived from the Modular Coil Asm Specification (in progress).

#### Electrical

- Partial Toroidal electrical breaks shall be provided between adjacent modular coils within a field period (AA, AB, BC).
- Electrical breaks are required between adjacent modular coils in adjacent field periods (CC). [Ref. GRD Section 3.2.1.5.2b to be revised]
- Toroidal electrical breaks must be able to withstand an applied voltage of 150 V (ref. GRD Section 3.2.1.5.3.6).

#### Structural

- Carry loads up to 15-ksi compression, 4-kip/in shear
- Maintain a "no slip condition" under the bolts (friction joint)

#### Assembly

- Position the coils accurately
- Minimize gaps

#### Interface C-C



#### Winding Form Modification



MAY BE PART ONLY OR PARTIALLY AS SCALE 0.12



#### Winding Form Modification



VIEW D - D TYPE C WINDING FORM VIEW OF C-C FLANGE, DATUM E MAY BE PART ONLY OR PARTIALLY ASSEMBLIED SCALE 0.12 -SEE DETAIL C

#### Bolted Joint Asm (SE140-190-R2)





- Fiber-optic strain gages used to check analysis, monitor changes in performance
  - Gages unaffected by magnetic field, need no additional electrical isolation
  - Significant testing indicates some scatter on absolute measurements but very good repeatability over many cycles, at LN2 temperature
  - Gages can be installed in studs (.02 hole EDM-ed) and calibrated to provide very accurate indication of stud preload during operation



Trial installation of fiber optic gage in 1.375 dia stud

CC	Shim Length	No Bolt
Hole #	Hole to Bottom	Shim
1	2.75	
2	2.75	
3	2.75	
4	2.75	
5	2.75	
6	2.75	
7		2.75
8	2.75	
9	2.75	
10	2.75	
11	2.75	
12	2.75	
13	5.00	
14	5.00	
15	3.75	
16	3.75	
17	5.00	
18		5.00
19	3.75	
20	3.75	
21	3.75	
22	3.75	
23	3.75	
24		3.75
25	5.00	
26	5.00	
27		3.75
28	3.75	
29	3.75	
30	3.75	
31	3.75	
32	3,75	
33		5.00
34	5.00	
35	3,75	
36	3,75	
37	5.00	
38	5.00	
39	2.75	
40	2.75	
41	2.75	
42	2.75	
43	2.75	
44	2.10	2 75
45	2 75	2.15
40	2.75	
47	2.75	
48	2.75	
40	2.75	
49 50	2.10	
50	2.10	

#### C-C FLANGE SHIM LAYOUT







- Drawing SE140-055 defines inboard compression shims template
- Insulated, weld to flange one side



SCALE 0.50





• Optional concept reduces no. shims, uses spherical seat feature





NCS National Compact Stellarator Experiment

Development activities conducted at UT Magnet Development Lab (MDL):

- Mock-up construction
- Weld access for AA/AB/BC
- Access studies for CC



# The Design:

- Totally bolted, electrically isolated
- 6 top and 6 bottom inboard flange holes, with tapped holes in one flange and a thru holes in mating flange
- "Reasonably" tight fitting bushings
- Nut options: Superbolt, Hex, Hydraulic Nut w/ lock nut



# **Design Issues:**

- Physical ACCESS
  - Initial installation of bolting hardware
  - Re-Torquing of nuts (for all flange interfaces)
- Choice of ACCESS location
  - Top and bottom, inboard, between TF coils
  - Top and bottom, outboard, at "B" coil
  - Top and bottom, outboard, thru back of "C" coil
- Risks associated with ACCESS location
- Measuring and installing bushings



















### **C** – **C** Interface



### Top and bottom, inboard between TF coils:









# Top and bottom, inboard between TF coils:

- Visually clear line of sight, directly above and between TF openings on either side
- Easiest access and most comfortable working position
- Lowest risk of a worker damaging any external tubing, headers, electrical hardware, etc...
- Longest distance to reach the bottom-most nut
- Access opening is more restricted

### **C** – **C** Interface



### Top and bottom, outboard at "B" coil:









# Top and bottom, outboard thru back of "B" coil:

- Most direct access to nuts
- Shortest distance to reach the bottom-most nut (19"), good possibility of a worker (small in stature, with long arms) being able to use a hands-on approach when installing bolt kit
- High risk of a worker damaging some of the external tubing, headers, electrical hardware, etc... by having to climb around the shell and lay horizontally and try to wedge down into the opening
- Does not allow a direct line of sight for worker, video camera / light system will be needed

# **C** – **C** Interface



# Measuring, fabricating, installing bushings:

- A video system (flexible cable) with lighting will be needed to read the bushing gage for measuring hole eccentricity
- An alternative is to wrap the outer gage surface with litmus or fuji paper so when the gage rotates and stops, a line marks where it touches the hole inner diameter
- The finished bushing:
  - Slides down the strain gage sheathing onto stud
  - Is oriented accurately to the hole
  - Slightly inserted into flange hole
  - Bearing washer, hex nut slides down cable
  - Nut is tightened to press the bushing into hole
- Bushing installation nut is removed, permanent nut is re-installed with complete washer set

# **C** – **C** Interface



# **Proposed R&D:**

Prove feasibility of making and installing a bushing Design, develop, and acquire necessary tools and hardware – identify and acquire necessary video / lighting components Field test tooling, video equip to make and install bushings

← 1 Month → ← 1 Month → 1 Month →

Manpower – PJ (.5), Gary (.25-.5), Joe (.25), Jim (.25), Bob (.25) = 1.5 – 1.75 for 4 months

- Feasibility study will be to measure and install a bushing in an enclosed "box" using manipulator, video camera mounted in side and light inside.
  - Determine most accurate method of measuring bushings
  - Determine how to orient / register bushing with hole
  - Determine if bushing can be "seated" using a nut
- Design and development stage will involve:
  - Manipulator fabrication or modifications
  - designing controls for moving, rotating, etc... video system

Field testing ideally involves using a C-C assembly in a vertical position with a B coil to see if there are any surprises due to mistakes in the coil castings - and also using the "actual", out-of-round flange holes



- Based on the design of 6 top and 6 bottom holes, 4 of the 6 holes appear to be accessible for making tight fitting bushings and bolting the joint with a reasonable effort.
- 2 of the 6 holes will require a difficult and time consuming effort to accomplish the bolted design.
- R&D tasks have been identified and planned to insure the success of the bolted design.
- Bottom Line: It is feasible to make the bolted C-C joint



Inboard interface FEA model developed for different C-C options:

- Six or twelve additional bolts
- 1.375 or 1.5-in diam bolts



## Options to restrain movement of inboard leg.

- By adding 6 to 12 bolts on the inner leg, the inner leg motion should be reduced significantly
- (model on right has 12 bolts added north and south of the midplane.



### **Contact Sliding regions**



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# Friction = 0.04 on Inner-leg region



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Sliding is 19 mils

### Friction = 0.4 everywhere on flange



#### **ADDED 12 Inboard Bolts**

Inner most bolts see 2.7 Kips

Sliding is less than 1.3 mils



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FLIARATOR EXPERIMENT

# Friction = 0.04 on Inner-leg region,



### mu = 0.4 everywhere else

C-C Bolt Preload & EM-Driven Bolt Shear Load with 12 added in-board bolts and perfect fitup



#### **ADDED 12 Inboard Bolts**

Inner most bolts see 3.4 Kips

Sliding is less than 2.4 mils



ANSYS 10.0A1 AVG ELEMENT : STEP=2 SUB =6 TIME=2 SLID IN (AVG) DMX =.832E-03 SMX =.002414 n 268E-03 .536E-03 .805E-03 .001073 .001341 .001609 .001877 .002145 .002414

ANSYS 10.0A1 ELEMENT SOLUT STEP=9999 CONTSTAT (NOA RSYS=0 PowerGraphics EFACET=1 DMX =.815E-03 SMX =3 FarOpen NearContact Sliding Sticking

# Max sliding and bolt shear table



Bolt Size (in)	Inboard Friction	# of inboard bolts	Max sliding distance (in)	Max Shear Force (kips)
1.375	0.4	0	0.0065	2.8
1.375	0.4	6	0.0047	2.4
1.375	0.4	12	0.0011	2.7
1.375	0.04	0	0.0199	4.9
1.375	0.04	6	0.0143	4.5
1.375	0.04	12	0.0024	3.5
1.5	0.04	6	0.014	4.7
1.5	0.04	12	0.0024	3.8
1.375	Imperfect fit-up (5 mil gap)	0	0.0193	3.3

• Number of bolts is the total number added: 12 bolts means 6 bolts added above and below the mid-plane.

• Little difference in sliding or shear force noted between the 1.375" and the 1.5" bolts: Contact stiffness explains shear force (next slides)

# Problem discovered in May 2007

- "Following the presentation of numerous global model results which showed high shear loads in some of the bolts, a detailed review of the contact element characteristics uncovered a defect in the model.
- The default contact element shear stiffness (~0.17E11 N/m3) was found to be too soft, and flange faces slipped when they should have been stuck.
- Over-riding the default shear stiffness value with incremental increases produced lower bolt shear loads and longer computer run-times for the representative A-A interface.
- A shear stiffness of 5E11 N/m3 seems to provide a reasonable compromise in accuracy and run-time.



## **Case Study:**

NCSX NATIONAL COMPACT STELLARATOR EXPERIMENT

## **Three 1.5" Innermost Bolts Added**



## **Shear Force on Inner Leg of CC**



NATIONAL COMPACT STELLARATOR EXPERIMENT

### **Inner Leg Bolts Only**





### **Contact Slip Plots**





The contact stiffness overestimates the shear force but has little effect on sliding.

# **Unbolted Inner leg Shims (shear)**







#### Horizontal Shear

#### Vertical Shear

# **Analysis Summary**

- NCSX NATIONAL COMPACT STELLARATOR EXPERIMENT
- Adding 12 bolts to the CC flange essentially eliminates inner leg sliding (< 2.5 mils for all friction cases.
- All 12 bolts are stuck and see limited shear from flange/flange stiffness/deflection.
- Going to 1.5" bolts has limited effect.
- The unbolted region will see limited shear (less than 6 ksi) if 12 bolts are used.
- A more detailed sub-model of unbolted inner leg shims may be needed to determine weld strength to prevent shims from dislodging.
  \*Positioning holes can also be used to hold shims



Task	Description	Finish
IH1-0000	PDR C-C Inboard Interface	7-Aug
1421-3143	Issue dwg w/ additional holes (SE141-148)	17-Aug
1421-3140	Issue dwg for C-C shims (SE140-055)	
1421-3145	Mockup and access studies	8-Oct
	Develop inboard bolt installation concepts	30-Oct
	Fab / procure hardware for inb bolt installation	28-Dec
	Conduct field trial on actual CC or BCC fit-up	30-Jan
1421-3144	FDR C-C Inboard Interface	15-Feb



- Are the requirements defined? What is the proposed design? Additional holes, shim layout complete
- What is the status of mockup and access studies? Bolt installation is feasible, development + testing planned
- Is the analysis consistent with proposed design? Twelve additional bolts eliminates need for sliding shims
- Have prior design review chits been addressed? Bolt asm, welded shims FDRs addressed relevant issues
- Have all technical, cost, schedule, and safety risks been addressed? Access tooling development planned



# Friction = 0.4 everywhere on flange NCSX

# through alumina shims.



### **ADDED 6 Inboard Bolts**

Innermost 6 bolts are shown but not used in the calculation (shown as x's in the sliding picture)

Inner most bolts see 2.4 Kips

Sliding is 4.7 mils



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# Friction = 0.04 on Inner-leg region,

# mu = 0.4 everywhere else



### **ADDED 6 Inboard Bolts**

Frictionless In board leg

Peak Shear is 4.8 Kips

Sliding is 14 mils



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## **Positioning hole on CC interface**







#### Bolted Joint Asm (SE140-190-R2)





#### Shim (SE140-040-R0)

