

# NCSX FPA Metrology and Dimensional Control Overview

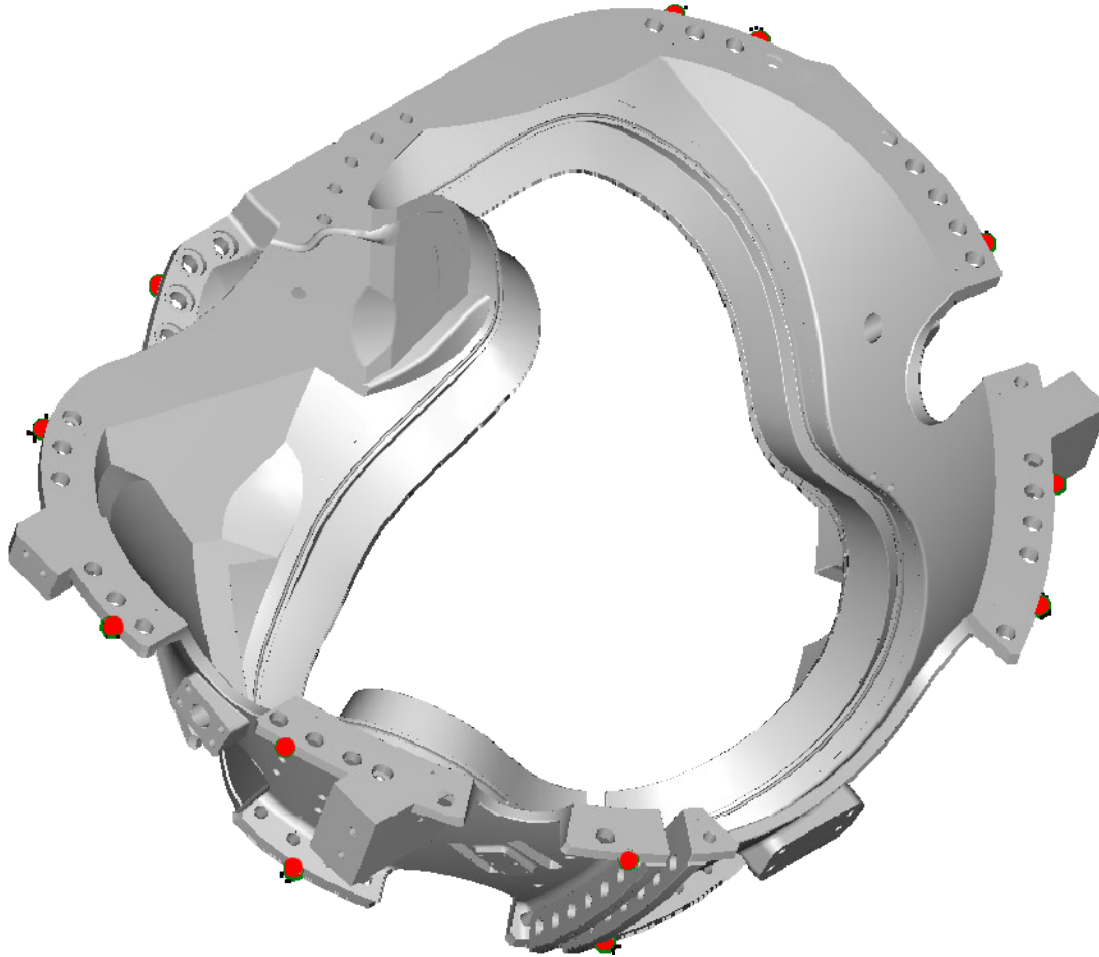
Haange/Klinger visit to PPPL

October 6-7, 2008

# Dimensional Control Overview

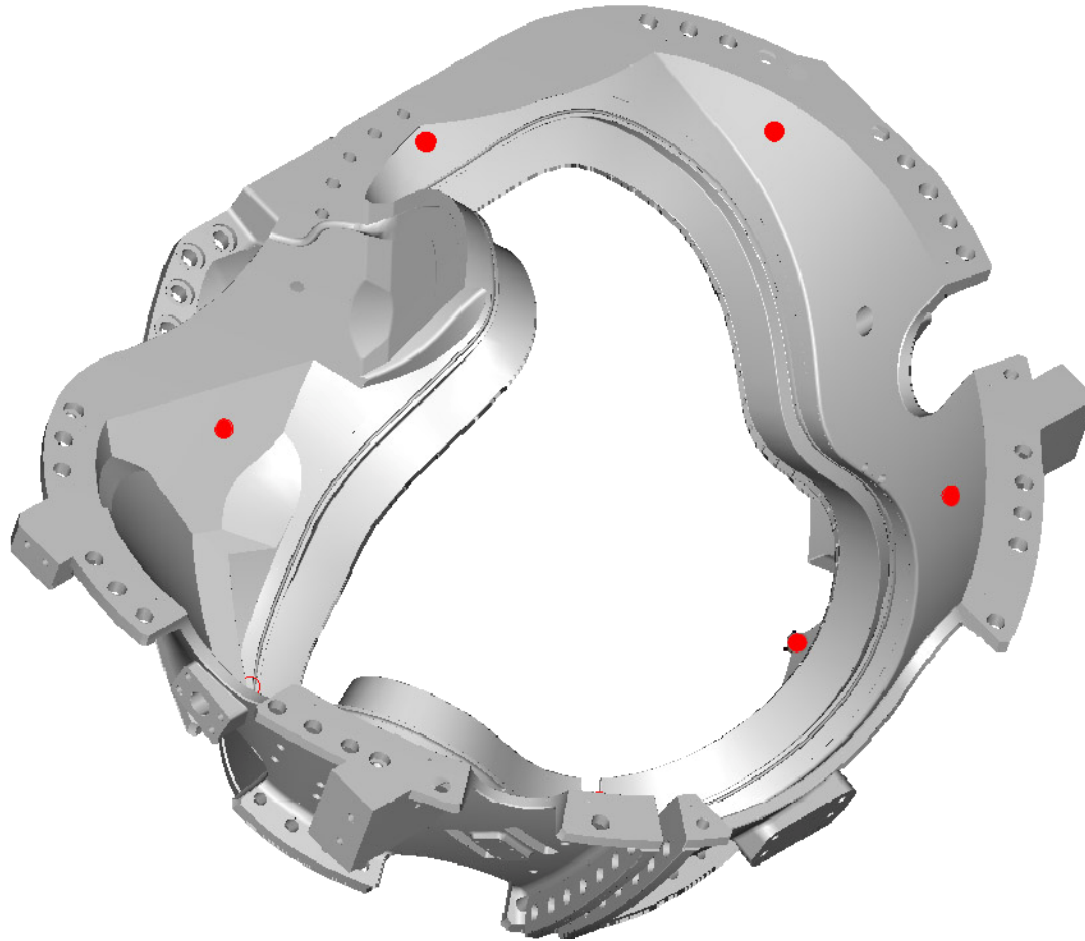
- Goal: Current center of Modular Coil Winding Form (MCWF) positioned within 1.5mm [.06in] of Theoretical Position
- After coil fabrication, Windings cannot be measured directly
- Set of monuments (“conical seats”) relate points on MCWF to HPA global coordinate system
  - Assumptions/Parameters:
    - Measurement accuracy during winding.
    - Deviations during winding.
    - No movement of windings after lacing.
    - No distortion during VPI and curing.

# Coil Monument History



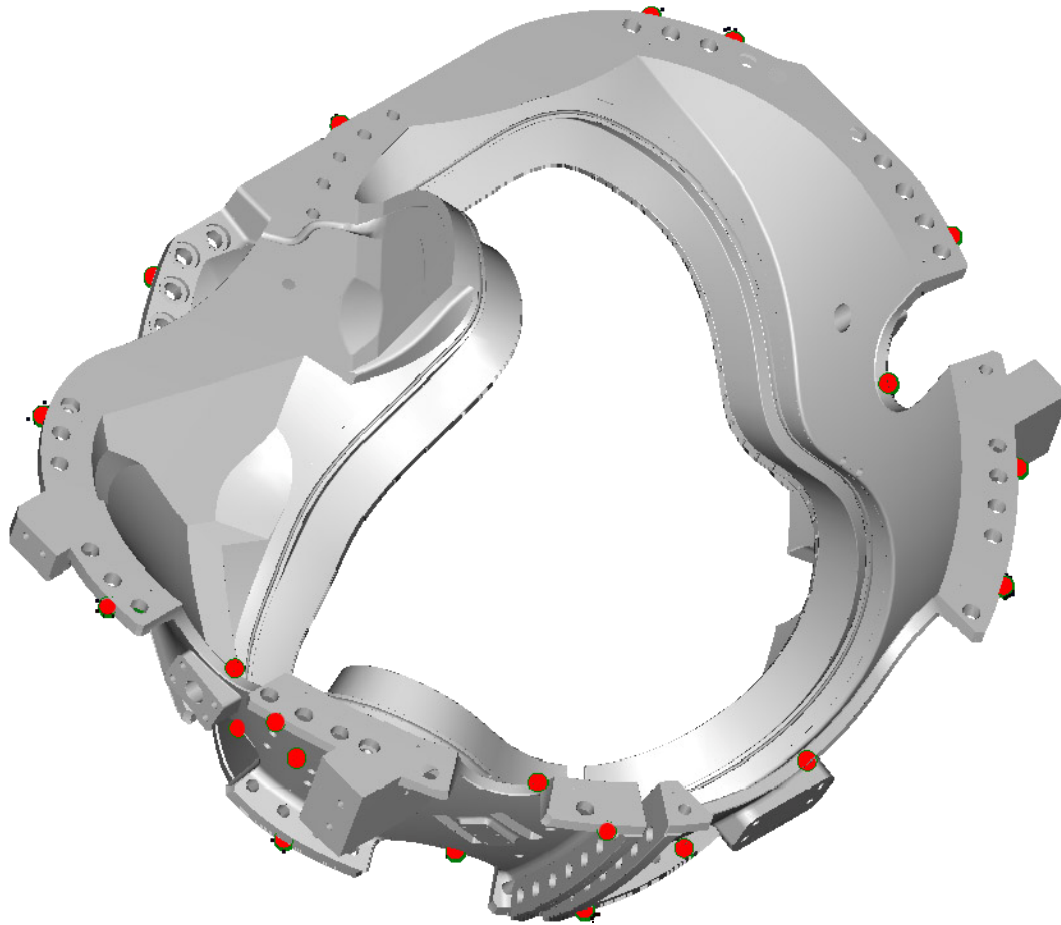
MTM flange tooling balls used for initial inspection and alignment

# Coil Monument History



PPPL adds 15mm conical seats for subsequent alignment during winding

# Coil Monument History



After winding, metrology transitions back to flange tooling ball locations and adds body tooling balls

# Pre-Measurement Process

- Quality of alignment is critical to the success of this step
- Modular coils can deform significantly as a function of their supports
  - Winding fixture (vertical, bolted)
  - HPA assembly position (horizontal)
- Before pre-measurement, modular coils must be twisted, or “racked”, into its as-wound shape as best as possible
  - Adjustments normal to flange
  - Gravity load of one coil
  - 0.005” RMS deviation on alignment to conical seats (ALARA)
- Measure tooling balls

# Pre-Measurement of Flanges and Monuments Follows Alignment

- Establish a network of global monuments attached to building
  - Use for relocating laser tracker
  - Use for resuming work after equipment powered down overnight or inadvertently bumped
- Alignment criterion for global monuments is 0.002" RMS deviation
- Measure all monuments
  - Multiple laser positions are necessary.
- Scan the appropriate flange

# Sample Alignment Report

Verisurf Alignment Report

## Verisurf Alignment Report

Part Name: 072707 B1 COIL ON MTM  
WEDGE BWARP-AA  
Alignment Name: 072707 b1 warp Auto  
Align 1  
Coord System: WORLD  
Date: 08/02/07



### Fit Results

Name	DX	DY	DZ	3D
3D Point 10	-0.002	-0.001	0.003	0.003
3D Point 11	0.001	0.002	0.000	0.002
3D Point 12	-0.002	0.000	0.001	0.003
3D Point 13	-0.003	-0.003	0.001	0.004
3D Point 14	0.000	-0.003	-0.002	0.004
3D Point 15	0.000	0.000	0.001	0.001
3D Point 16	0.001	-0.002	0.001	0.003
3D Point 17	0.004	0.006	-0.004	0.008
3D Point 18	( 0.006 )	( 0.010 )	( -0.012 )	( 0.017 )
3D Point 19	0.002	0.002	-0.002	0.004

### Fit Summary

Total Points: 9	DX	DY	DZ	3D
Maximum Deviation:	0.004	0.006	0.003	0.008
Minimum Deviation:	-0.003	-0.003	-0.004	0.000

Deviation Range:	0.006	0.009	0.007	0.008
Average Deviation:	0.000	0.000	0.000	0.004
RMS Deviation:	0.002	0.003	0.002	0.004
Standard Deviation:	0.002	0.003	0.002	0.002

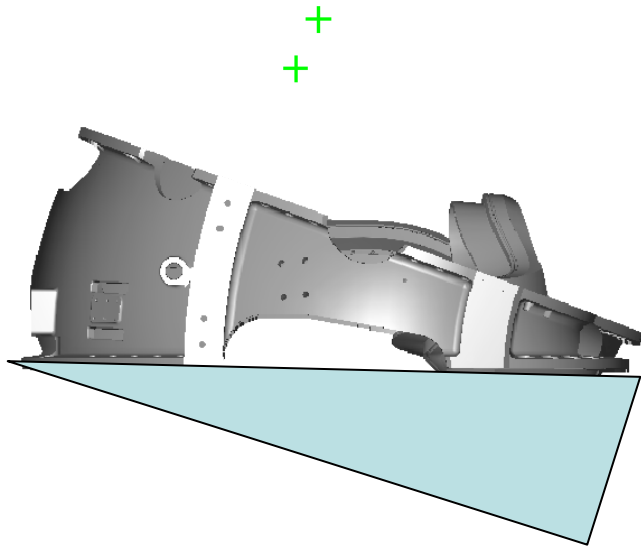
### Transformation

	X	Y	Z
Translation:	31.221	103.049	26.283
Matrix I:	0.765	-0.015	-0.644
Matrix J:	0.011	1.000	-0.011
Matrix K:	0.644	0.002	0.765



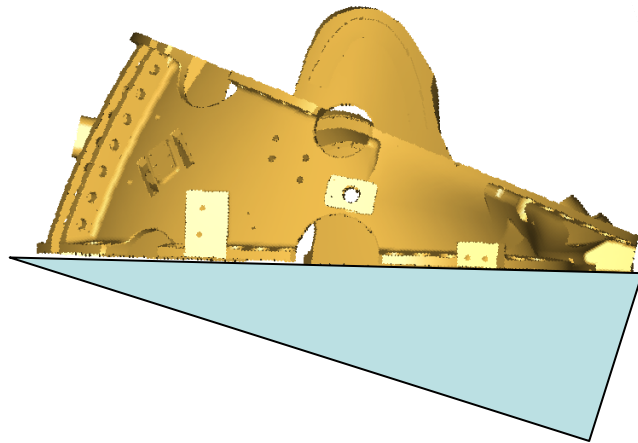


# Metrology for Assembly Process



- Wedge 1, Coil A1
  - Rack
  - Clamp
  - Flange scan
  - Measure monuments
    - Send data to Back Office for shim calculation

# Metrology for Assembly Process

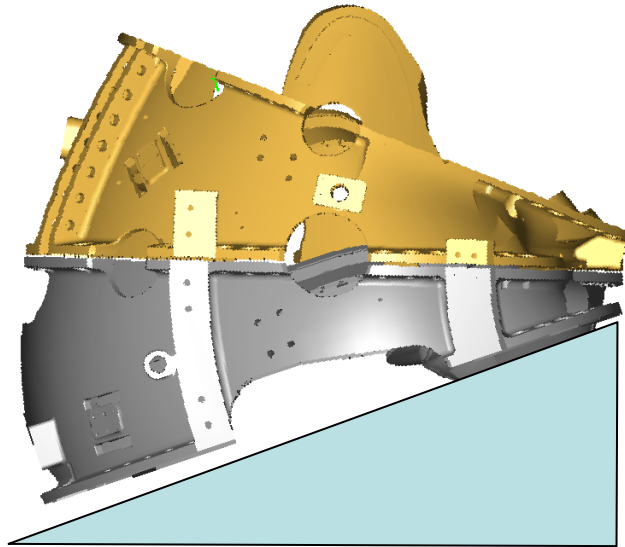


- To expedite our process, we complete steps for B-C interface in parallel
- Wedge 2, Coil B1
  - Rack
  - Flange scan
  - Measure monuments
    - Send data to Back Office for shim calculation

# “B” Coil is Added

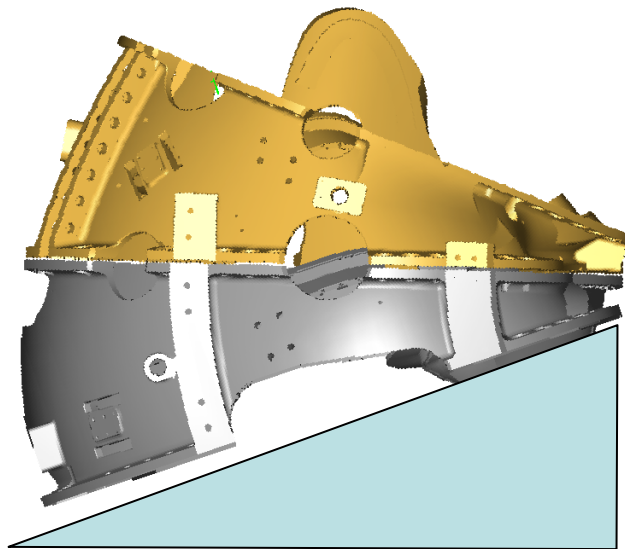
- Shims establish shape of coil and positioning normal to A-B interface
- Measure monuments on coil to verify
  - opportunity to correct shim thicknesses
- Alignment calculator used for positioning “B” coil in plane of A-B interface
- Initial shim weld, position “B” coil, torque bolts, measure, final shim weld, measure
- Accuracy goal is 0.012” deviation of monuments from theoretical position
- **How did we do?**
  - **78 monuments measured, 2 outliers [0.014”, 0.015”]**

# Metrology for Assembly Process



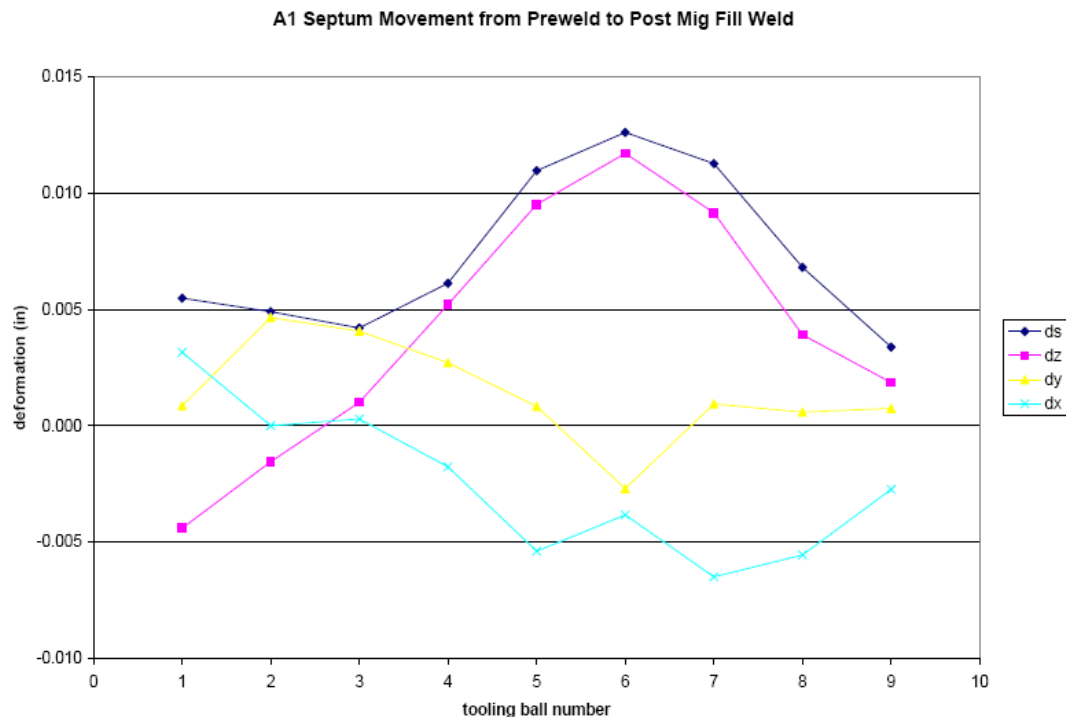
- Wedge 1, A-B fitup
  - Align X-Y using spreadsheet
  - Test shims from Back Office
  - Measure nose puck heights using nose shim template

# Metrology for Assembly Process



- Realign X-Y
- Weld inboard side of nose shims
- Torque bolts to 100%
  - Re-measure monuments after each step
- Scan B-C flange
- Increase wedge incline to 40 degrees for B-C fitup
  - Repeat previous steps

# Welding Process



- Separate coils, weld plasma side of nose shims
  - Monitor septum distortion during weld process

# “C” Coil is Added

- Follow same general steps as the A-B assembly
- Accuracy goal is 0.020” maximum deviation of monuments from theoretical positions
  - **HPA1: 100 monuments measured, no deviation greater than 0.015”**
  - **HPA2: 105 monuments measured, one nonconforming at 0.021”. Only three monuments with deviation greater than 0.015”.**
- We have implemented a systematic, repeatable method of achieving the project dimensional goals for half period assembly.

# Laser Measuring Tools

- Corner Cube (CCR)
  - 1.5" or 0.5" diameter
  - Sits in magnetic nest
  - 0.5" diameter, with special nest, mimics short shank tooling ball
  - Negligible positioning accuracy relative to nest
  - Global monuments are 1.5" dia. CCR in nest secured to building or HPA fixture
  - When nest placed in tooling ball hole, accuracy issues are same as for tooling balls – tightness of the hole
  - Possible blunders using 0.5" dia. CCR and special nest – does it remain seated in hole after grip is released? [air pressure in hole may act as spring]  $\sim .001''$  -  $.002''$  effect; difficult to recognize
  - Limited viewing angles



# Laser Measuring Tools

- Leica Surface Reflector (LSR)
  - Allows laser to measure to the center of tooling ball by creating a virtual center
  - Avoids problem of tooling ball or nest “releasing” during measurement
  - Limited view angles
  - Highly accurate

# Laser Measuring Tools

- Measure a sphere around a tooling ball (or 15mm ball bearing in a conical seat) using CCR in a nest on a wand
  - Best view, least accurate
  - Necessary for measuring conical seats
  - Qualification tests performed to assess accuracy of this technique
  - In-field checking of sphericity of measurement helps to eliminate blunders

# Photogrammetry Tools

- 90°, 45°, and 0° Tooling Targets
  - Replicate tooling ball shoulder-to-center offset
- Stick-On Codes
- Stick-On Targets (where necessary)
- GSI V-Stars software
- Nikon D2Xs camera (modified)

# Photogrammetry Summary

- Surveys using same tooling ball locations agreed with Laser Tracker measurements
- Significant time savings not realized
  - Steep learning curve for Back Office post-processing
- Survey timing
  - Targeting: ~1 hour (initial setup)
  - Photo taking:
    - ~12 min (single coil)
    - ~20 min (2-pack)
    - ~1 hr (3-pack)
  - Post-processing: ~20 min (after Driver File completed)

# Conclusions

- The “Right Tool” for the Job
  - Laser Tracker
    - Coil-to-coil alignments
    - Real-time control/driving
    - Discrete point measurement
  - Photogrammetry
    - Multiple point measurement in single survey
    - Deformation/distortion studies
  - CMM Arm
    - Non line-of-sight part feature characterization