

1-EFA10

KKS-Nr.:

Max-Planck-Institut für Plasmaphysik

Dok-Kennz.:

Date: 11. October 2007

MECHANICAL PRE- ASSEMBLY PHASES (OVERVIEW)

Step 1-1: Arrangement for equipment in the pre-assembly hall.

Ground outline for MST I/A and I/B and II: Lenght x Width = at the least 34 m x 21 m



Figure 1: CAD- calculation of required space for mounting operation.



Figure 2: The mounting-stand I/B with the coilsystem.



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STEP 1-2: CORRECT ASSEMBLY- SEQUENCE IN THE PRE-ASSEMBLY-HALL (HM)



Figure 3: The half-module is disposed for transport process.

1. HS02 – Sector + Thermal insulation-panel 1
2. NPC3 (THREADING)/ NSE-CASTING (Presentation and Application in the LAB)+ SPRAYING+ NSE-Manufactoring
3. HS01- sector + Thermal insulation-panel 2
4. NPC 4 (THREADING)/ NSE-CASTING+ SPRAYING + NSE- Manufactoring
5. PLC B
6. Thermal insulation-panel 3
7. NPC 5 (THREADING) /NSE-CASTING + SPRAYING + NSE- Manufactoring
9. NPC2 (THREADING)/ NSE-CASTING + SPRAYING + NSE- Manufactoring
10. PLC A
11. Thermal insulation-panel 4
12. NPC 1 (THREADING)/ NSE-CASTING + SPRAYING + NSE- Manufactoring

13. Assembly Central ring half –module + CSE.

14. Assembly LSE and PSE (Measurement- Application).

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Step 1-3: Transport and Handling operations in consideration with the 100 t- overhead crane in IPP.

- Hook height: 10,44 m
- Lifting capacity: max. 100 tons (upper limit: transport modul + cross beam brace)



Figure 5: HS02- sector transport with a 150 kN- flatcar. The flatcar will be used for transport between neighbouring halls.





Figure 4: Load- and motiontests with

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Step 1-4: PV- Support for HM- Fixation in the MST I.



Figure 8: Transport vessel- sector HS02 inclusive 1st panel of thermal insulation with 1000 kN overhead crane in stand I/B. The weight of HS02-sector is 2,5 t. Fixing HS02 sector with a bearing flange and support pillar.

Figure 9: Real flange scenario between HS01-sector and a mechanical structure in stand I/B.



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Step 1-5: Different structures for the Coil- Assembly in MST I



Figure 9: Interaction SAE-2, NPC4- Lifttraverse and headover crane (2003). SAE-2-motion training with a blue test item (mass 6000 kg)

cross beam



Figure 10: SAE-1 parking test without NPC3. The cross beam for coilparking is constructed by IMG, Rostock. Interaction between SAE-1, mobil crane, operating platform and headover crane.

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Step 1-6: Coil- Assembly NPS4 and NPS5 for HM.







Figure 11: Assembly heat insulation-sector 2 at plasma vessel. Crane handling NPC4 with SAE-1 and NPC4 -Fixing in the final position.

Figure 12: Threading NPS 5 with SAE-1 in the endposition.

Figure 13: Fixing NPC1 in the end position (stand I/B).

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Step 1-7: Assembly of the Central- Ring- structure for the HM.



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Figure 15: Set up test for the central ring- semi- module onto linear sliding frame. The weight for central ring- semi-modul is 7,2 tons.

Polted Connecti

Bolted Connection





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Step 1-8: Assembly of the LSE and PSE for the coilsystem



Figure 16: We need 4 lateral supports per half-module. This are also welding joints.







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Step 2-1: HM- Transportprocess. Fixation the PV in coilsystem.



Figure 17: Installation rod-link-system and suspension elements at the non-planar coils NPC 1,2,3,4,5 for plasma- vessel transport.

Figure 18: Plasma vessel sector 51HS02. Bearing flange solution (half-module- side) with fixation-point in a port at plasma vessel.

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Step 2-2: Transport process for HM with the modul- traverse



Linear sliding frame in two directions. The moving range is 400 mm (Correction of deviations for centre gravity)

Figure 18: Transport process half-module 5.1 (500 kN) with load carrying equipment and overhead crane.

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Step 2-3: Modul joining – process in the MST II



Figure 19: Operating platform for bolted connection between two semi- central rings.