

# **WBS 14**

## **Modular Coils**

D. Williamson – Design and Analysis  
P. Heitzenroeder – Winding Form Fabrication and R&D  
J. Chrzanowski – Modular Coil Fabrication and R&D  
D. Williamson – Cost / Schedule and Summary  
for the NCSX Team

**NCSX Performance Baseline Review**  
**November 18-20, 2003**  
**PPPL**

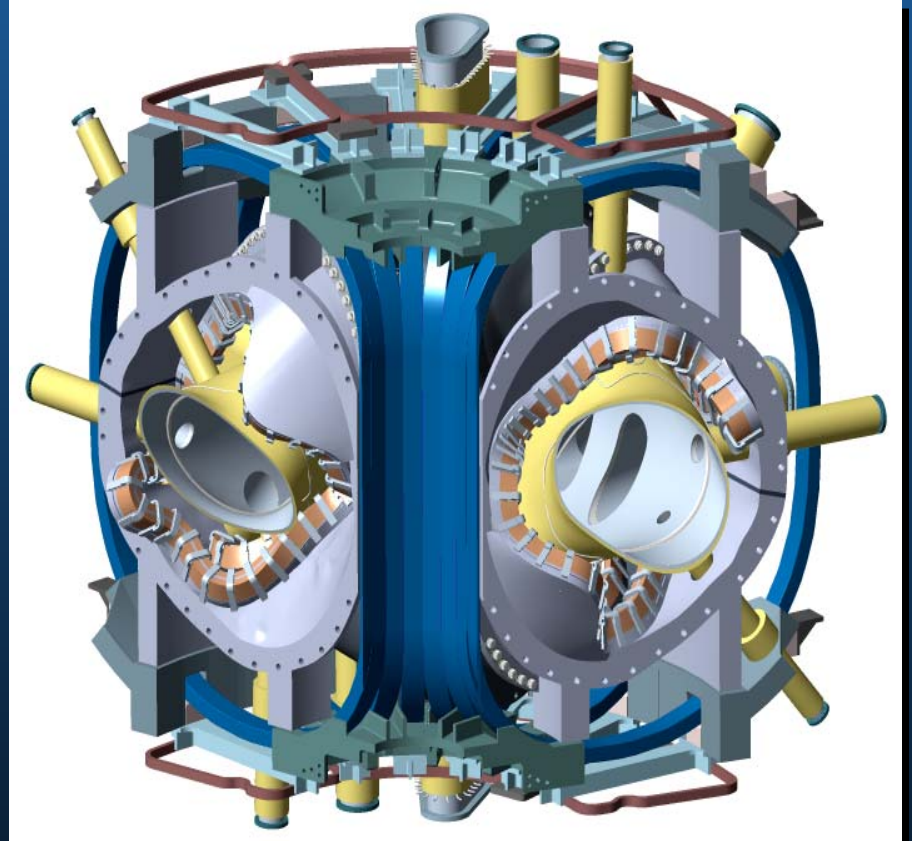
- **Modular coil system has improved significantly since CDR:**
  - **Winding center changed to improve physics, engr parameters**
  - **Introduced poloidal break; developed details for leads, cooling**
  - **Performed winding, potting, and properties tests on conductor**
  - **Engaged multiple vendors in winding form development**
  - **Developed design of winding fixtures and autoclave**
  - **Requirements, interfaces, and design basis established**
- **We are ready to proceed with final design**

# Presentation Outline

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- **Modular Coil Design, Analysis, and Implementation**
  - **System Requirements**
  - **Design Description**
  - **Analysis**
  - **Winding Form Manufacturing (P. Heitzenroeder)**
  - **Winding Facility and R&D (J. Chrzanowski)**
- **Cost and Schedule**
- **Summary**

- **Modular coil WBS includes:**
  - **Winding forms**
  - **Windings and assembly**
  - **Coil instrumentation**
  - **Winding facility**

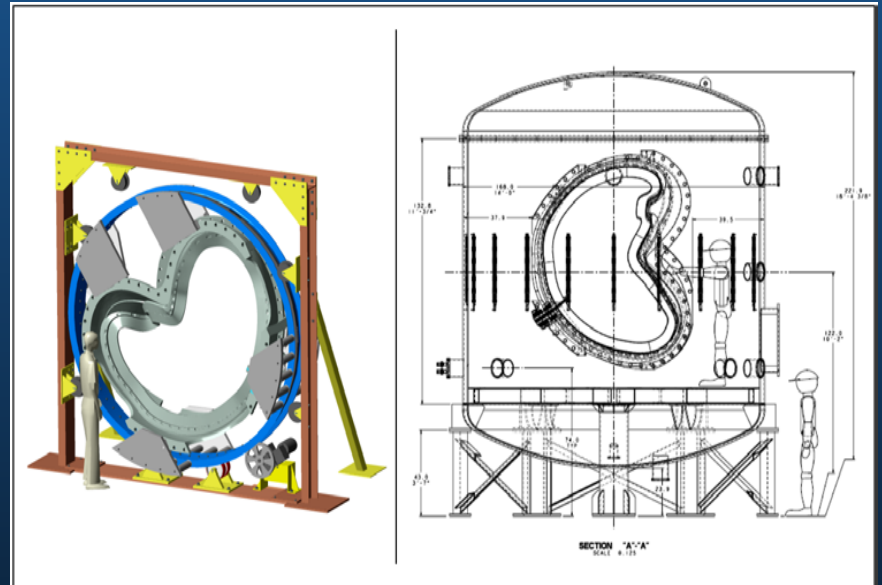


- **The winding forms provide an accurate means of positioning the conductor during the winding and vacuum-pressure impregnation (VPI) process**
  - **Machined surfaces within 0.020-in (0.5-mm) of CAD profile**
  - **Segmented for assembly and to meet electrical requirements**
  - **Provide access for NBI, ICRH, diagnostics, personnel**
  - **Support vacuum vessel, interface with PF/TF coil structure**
- **The coil windings provide the basic quasi-axisymmetric magnetic configuration**
  - **Field up to 2-T for 1-s with 15 min rep rate**
  - **Winding center accurate to +/- 0.060-in (1.5-mm)**
  - **Independent control of each coil type for flexibility**
  - **Instrumentation to provide feedback for coil protection system**

# Requirements (cont'd)

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- **Winding fixtures and tooling are required to position and support the conductor during fabrication**
  - **Fixtures interface with three coil shapes, provide access for conductor spools and tooling**
  - **Efficient and accurate**
- **Autoclave is required for “bag mold” vacuum pressure impregnation (VPI) process**
  - **Capable of <1-torr to 15-psig, heating to 135-C in <24-hrs**

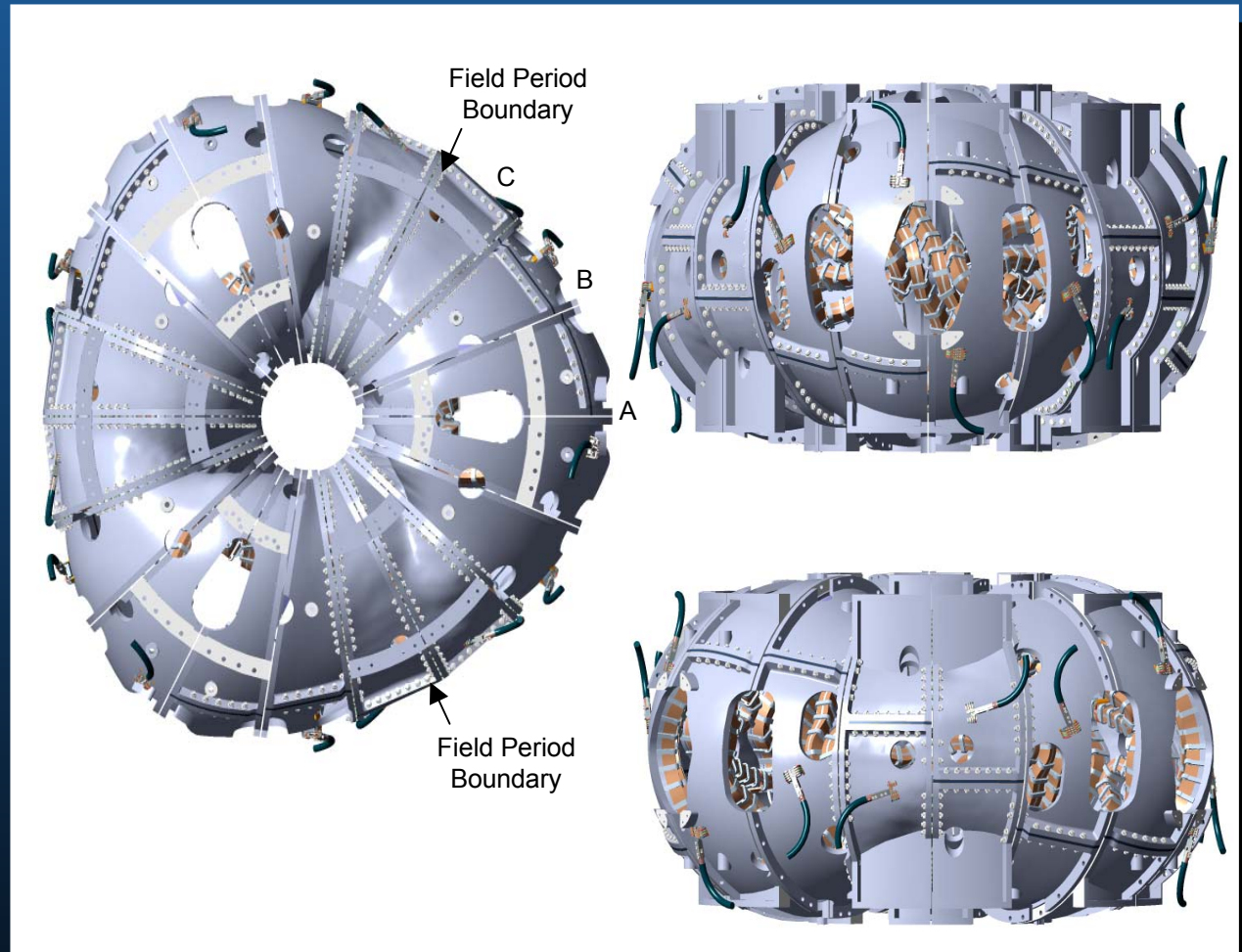


Ref: J. Chzranowski

# Modular Coil Assembly

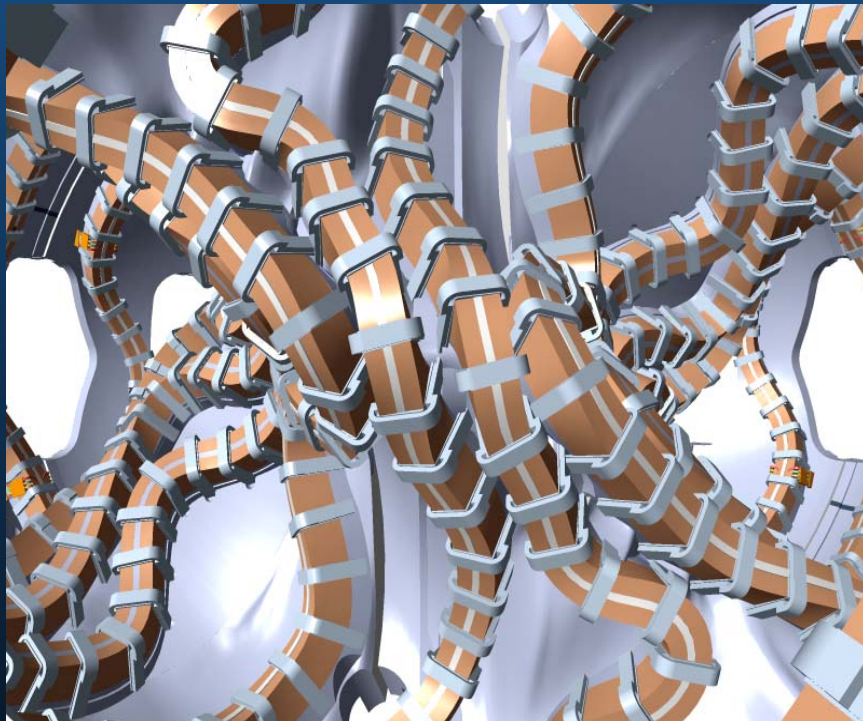
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- Integral shell composed of 18 modular coil assemblies
- Three field periods, 6 coils per period, 3 coil types
- Shell thickness = 1.5-in, can vary to meet stress requirements
- Total weight = 125,000-lb
- Each modular coil:
  - 1,900-ft of conductor
  - 48 coil clamps
  - 200 fasteners

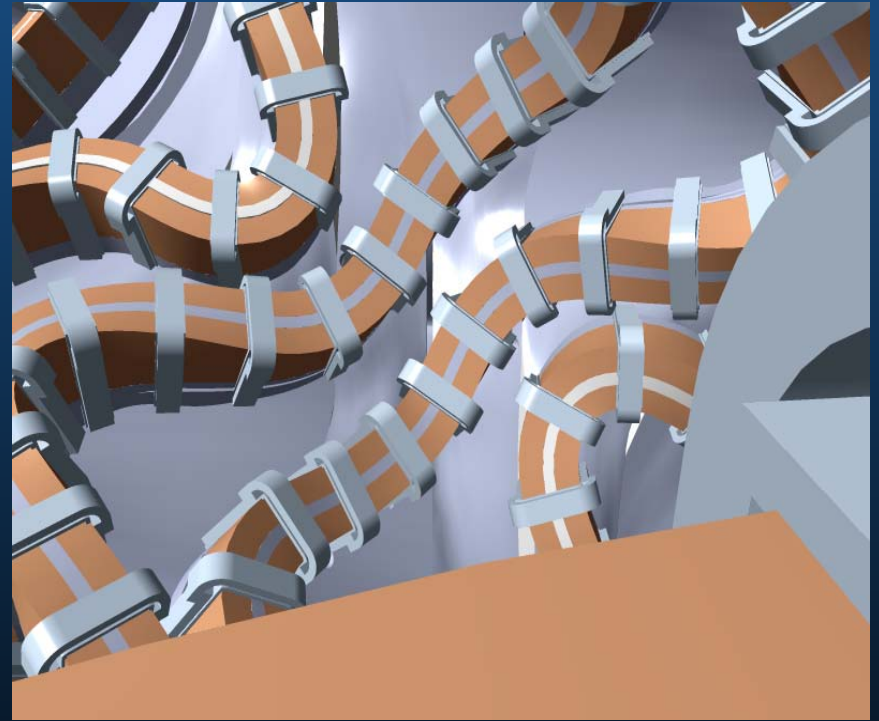


# Interior View of Structure

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Wide Angle View at Coil Type A-A

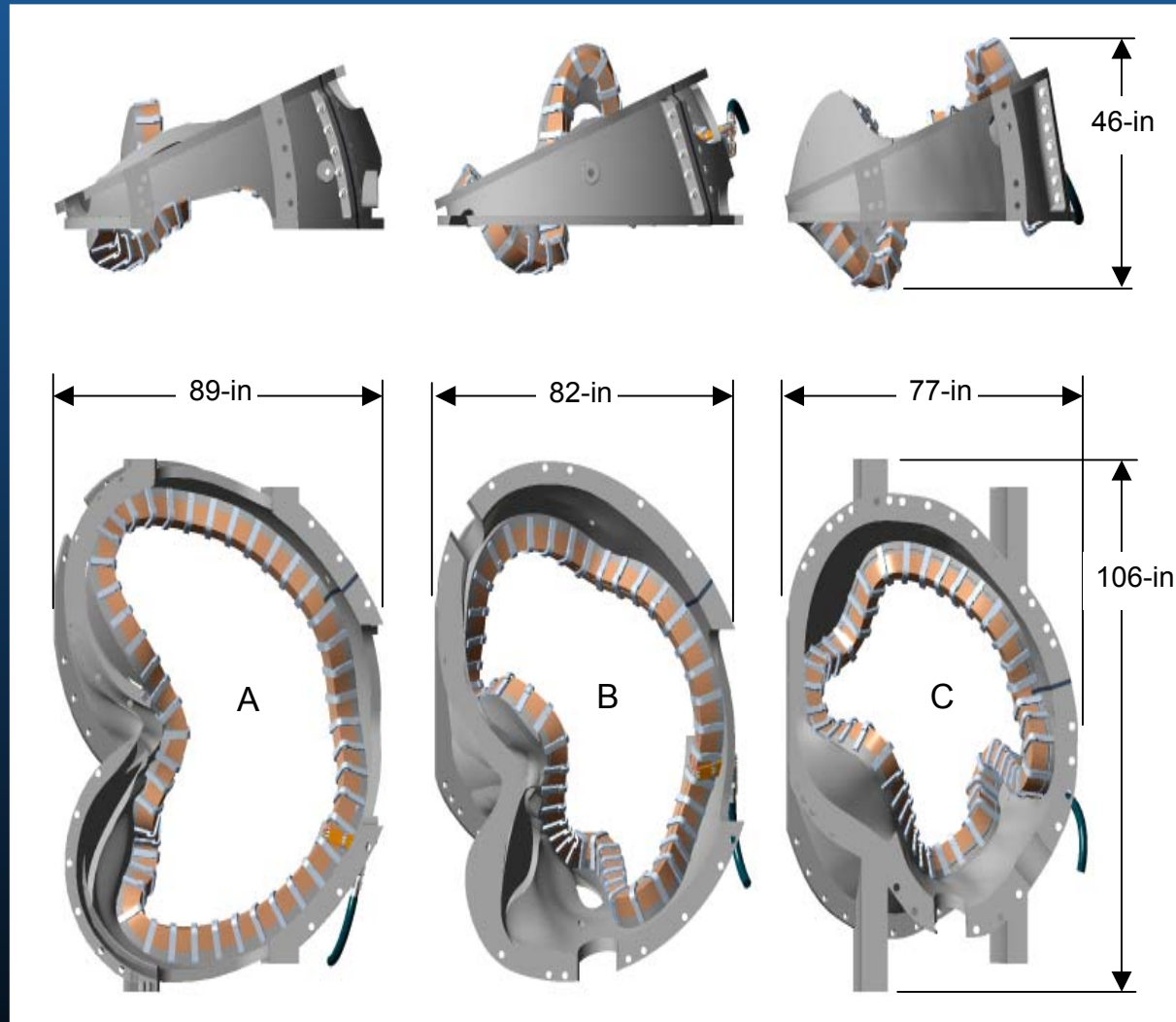


Wide Angle View at Coil Type C-C



# Modular Coil Types

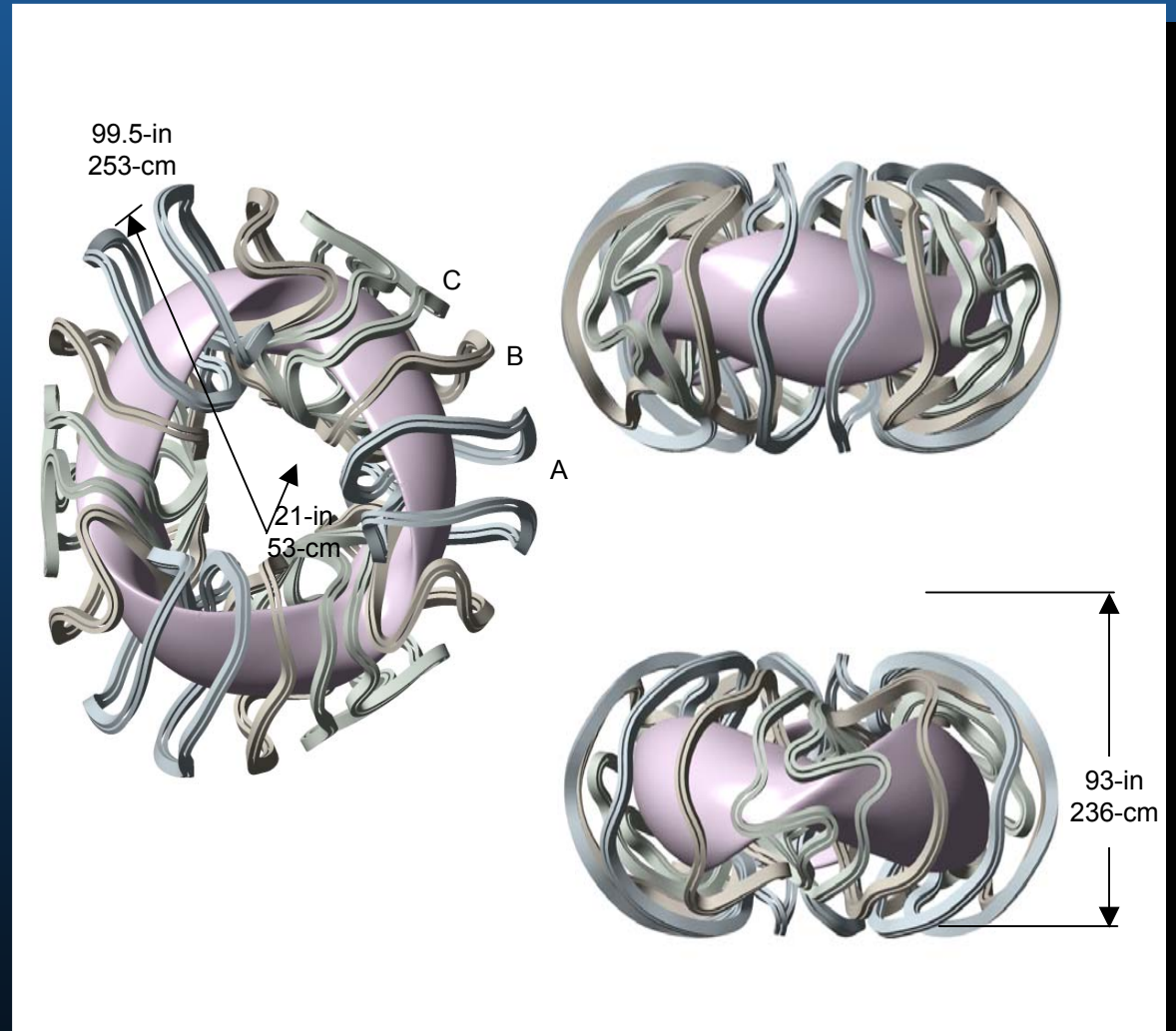
NCSX



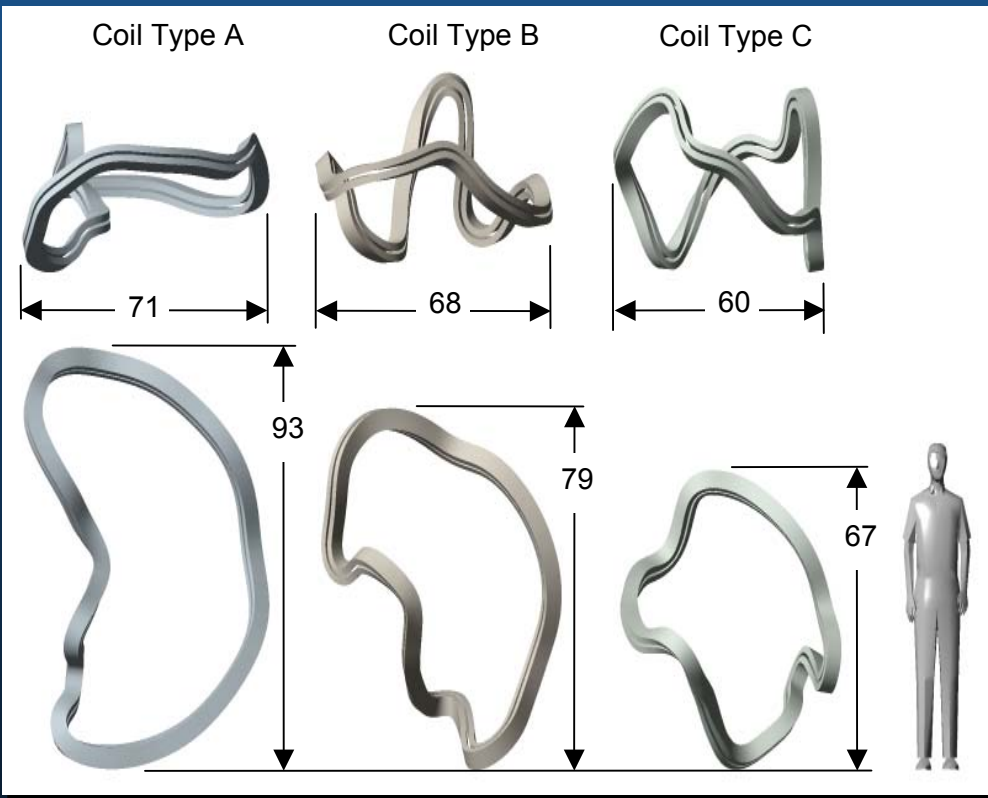
# Coil Configuration

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- Three field periods with 6 coils per period, for a total of 18 coils
- Shape developed through a physics optimization process that emphasizes plasma properties, geometry constraints, and current density limitations
- Coilset # m50\_e04



# Coil Geometry



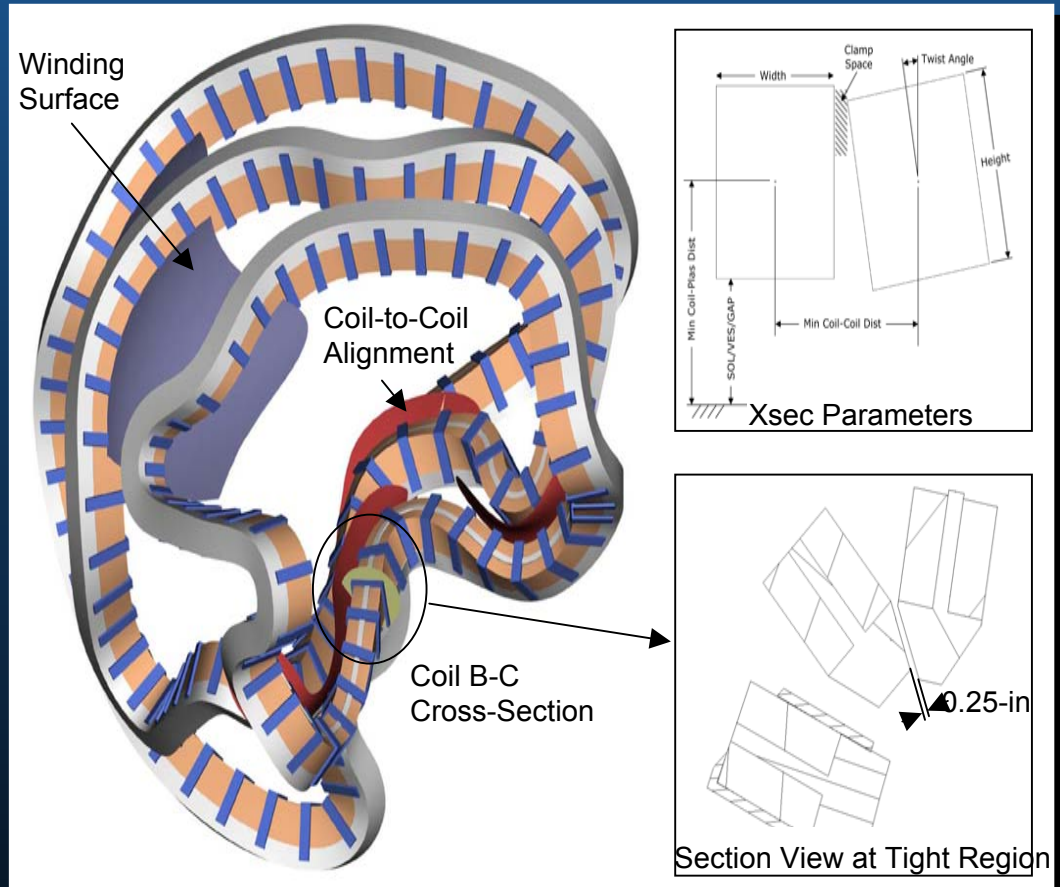
- **Min bend radius at winding pack surface is 2.5-in, 2.7-in, and 3.1-in for coils A, B, and C respectively**

Case m50_e04 Coil Parameters							
Coil #	A'	A	B	C	C'		
Coil Length (in)		291	283	263			
Min Coil-Coil Dist (in)	7.6	6.3	6.1	6.8			
Max Coil-Coil Dist (in)	35.0	36.4	30.7	26.6			
Min Rad of Curvature (in)		4.2	4.8	4.3			
Min Coil-Plas Dist (in)		8.8	8.1	9.0			
Max Coil-Plas Dist (in)		28.5	22.6	20.2			

# Cross-Section Development

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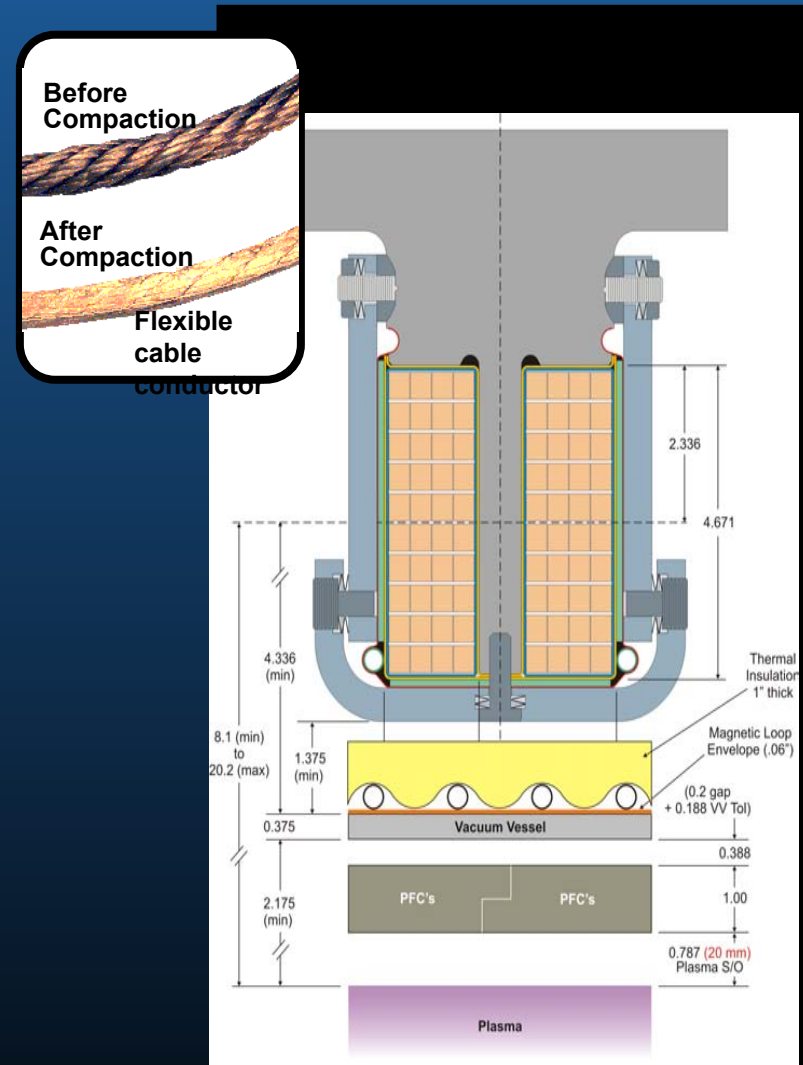
- Coil “twist” has been developed through an iterative process
- Resulting cross-section is normal to winding surface along most of coil length, but varies inboard to accommodate adjacent coils
- Some regions require taper in base of tee to avoid interference
- A study of finite build coil fields indicates twist adjustments are acceptable



# Winding Pack Configuration

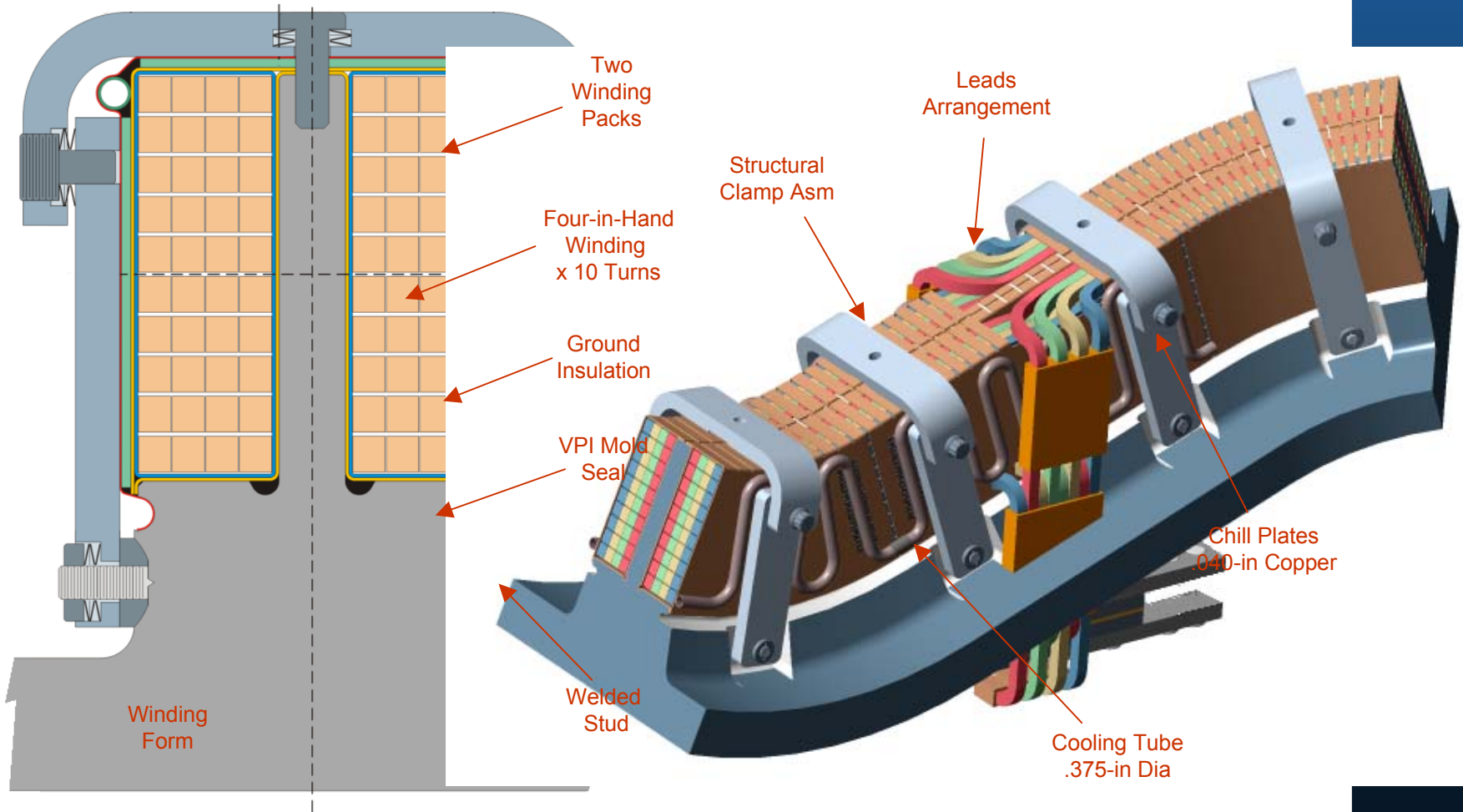
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- Parameters:
  - Coil Envelope = 2 x 1.675 x 4.671-in
  - Current / Coil = up to 831-kA-turns
  - Number of Turns = 20 (A, B) and 18 (C)
  - Max Current / Turn = 41.6 -kA
  - Conductor Size = .391 x .35 in (9.9 x 8.9 mm)
  - Cu Current Density = 15.1-kA/cm<sup>2</sup> (Max)
  - Conductor operating temp. range 85K-130K
  - Operating voltage = 2-kV
- Layout changed from CDR concept, a double-layer pancake, to 4-in-hand layer wound design
  - Reduced keystoneing due to smaller conductor
  - Low turn to turn voltage
  - Less time estimated to wind



# Winding Pack Configuration (cont'd)

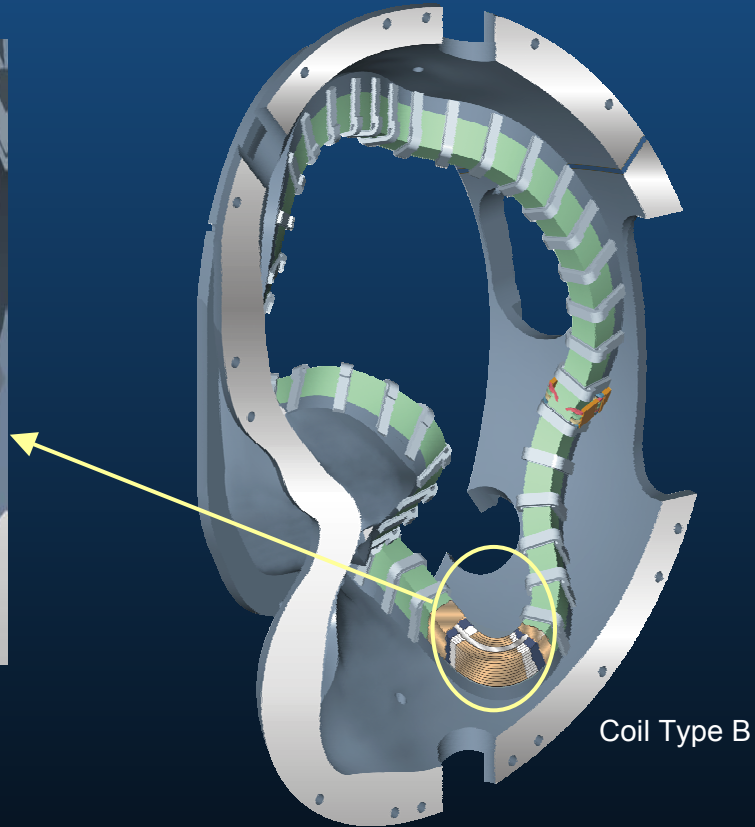
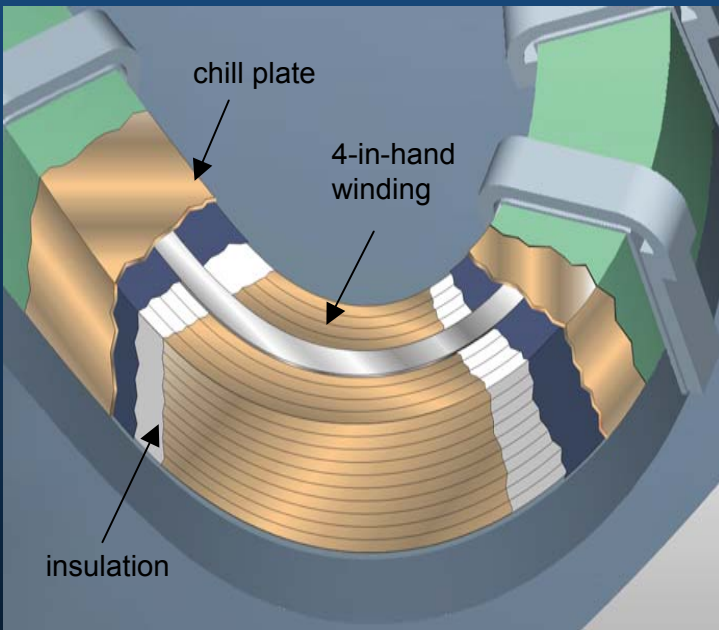
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# Conductor Insulation

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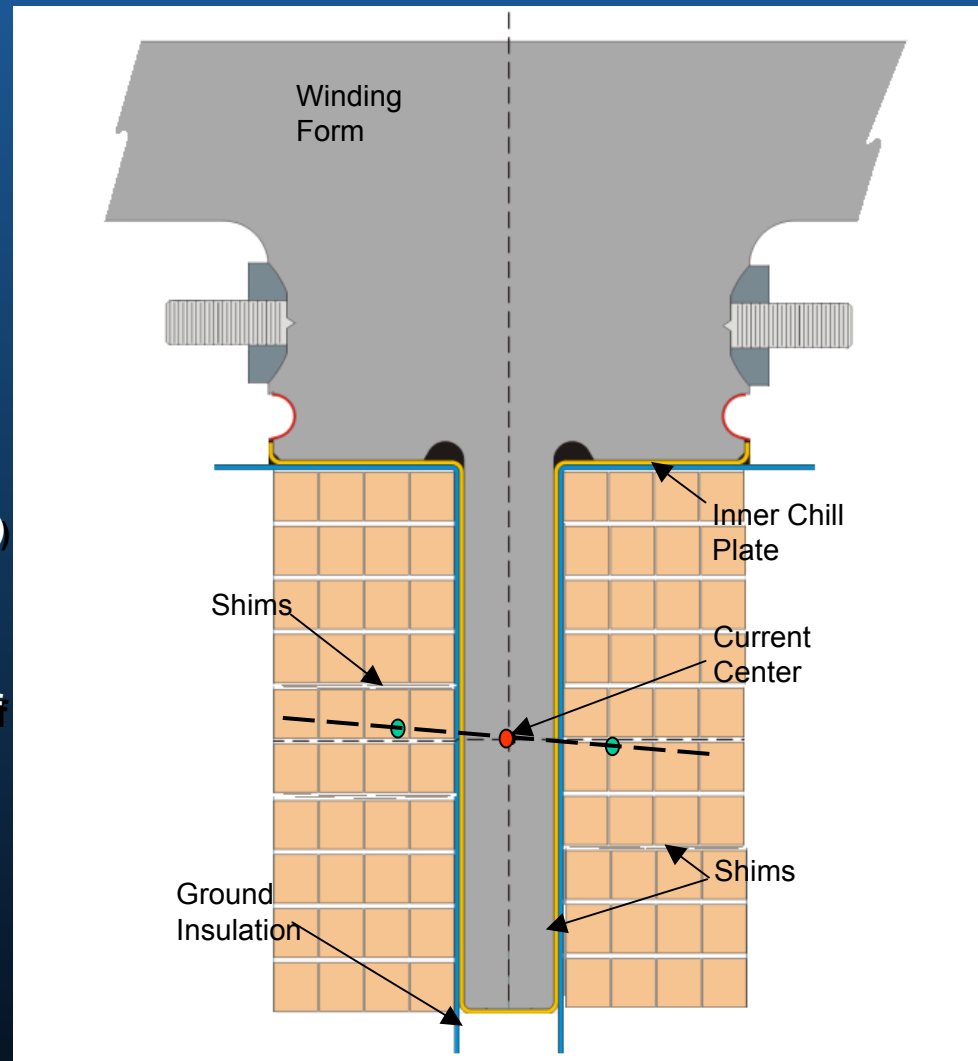
- Conductor insulated with 0.004-in nylon serve and two half-lapped layers of 0.004-in glass cloth (0.6-kV)
- Ground wrap consists of 0.030-in glass cloth and 0.008-in Kapton (2.3-kV)



# Winding Accuracy

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- Winding position is continuously monitored and adjusted to avoid tolerance stack-up
- Tolerance issues:
  - Machined surfaces of winding form are accurate to  $\pm 0.010$ -in (0.5-mm)
  - Conductor w/o insulation has a dimensional tolerance of  $\pm 0.010$ -in (0.5-mm)
  - Geometry requires up to 0.036-in (.91-mm) per layer allowance for conductor keystoneing
- Current center can be adjusted by use of shims between layers

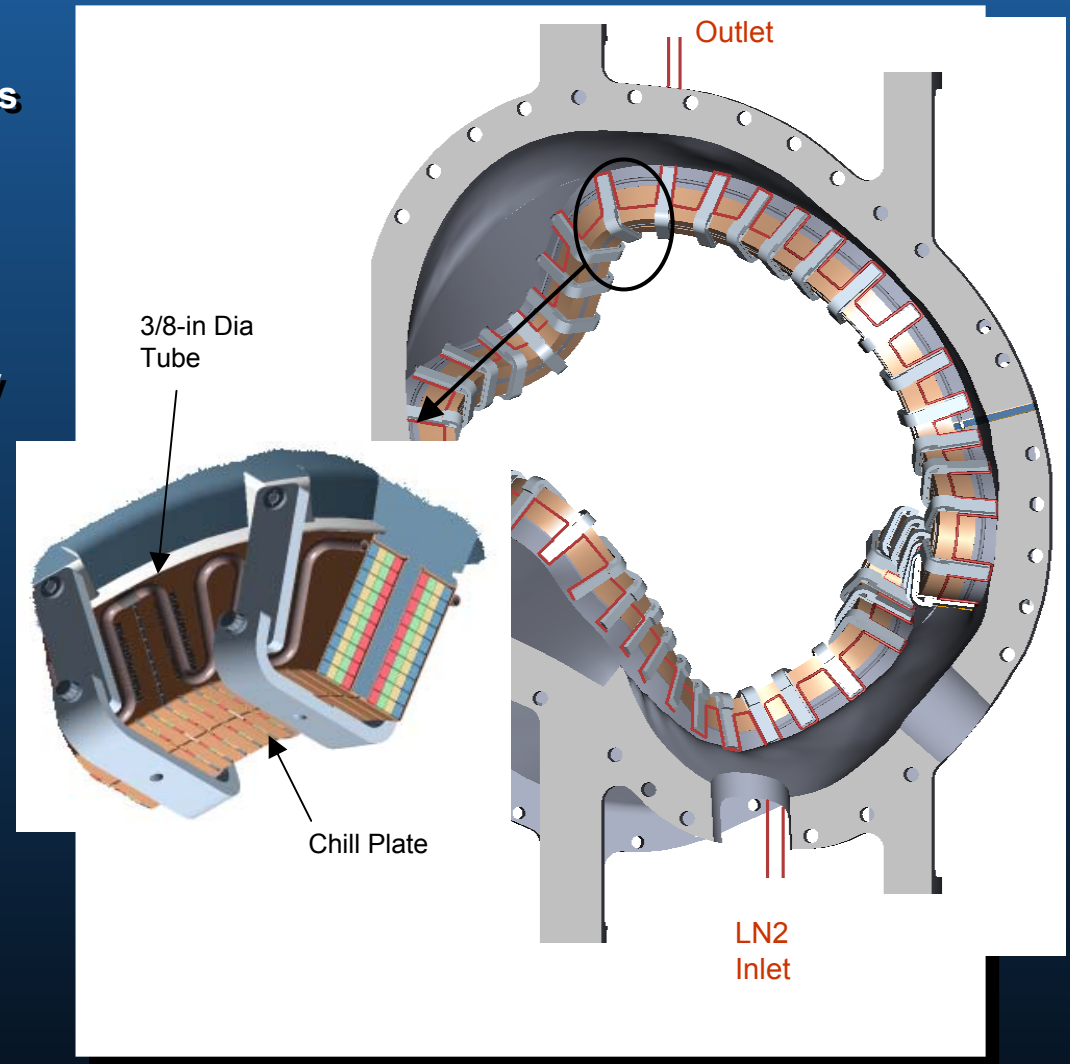




# Coil Cooling

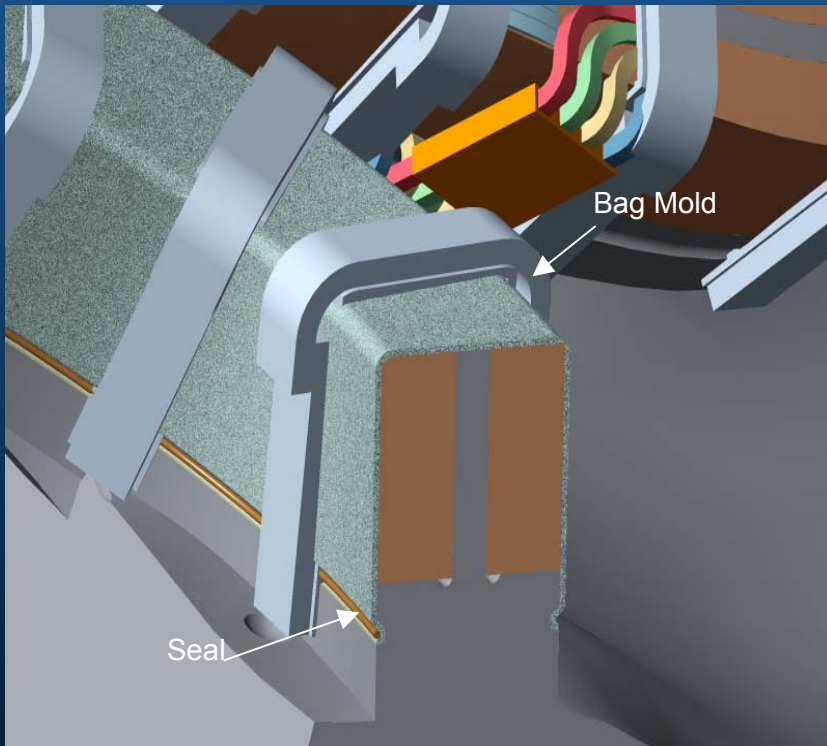
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- A thin chill plate is located on both sides of each winding pack to remove joule heating between plasma discharges
- Chill plate is cut in flat patterns from 0.040-in thick copper and formed around winding pack
- Chill plate is segmented and electrically isolated from winding form
- Outer plate is cooled by liquid nitrogen in tube bonded to surface
- Nitrogen enters the chill plate circuit at the bottom and exits near the top of each coil



# VPI Bag Mold Feature

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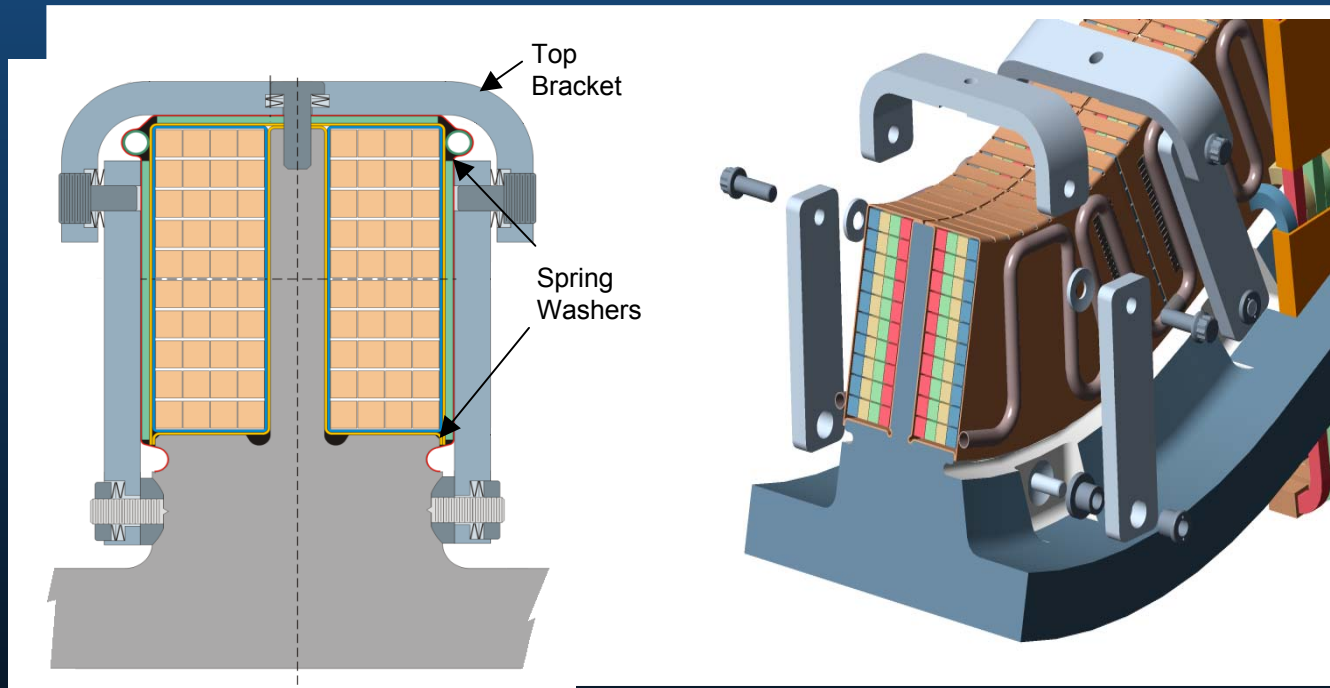


- VPI mold is composed of epoxy impregnated felt and silicon rubber tape
- Located between winding pack and clamps
- Sealed by pressing tube into continuous half-round or v-groove at base of tee

# Winding Pack Clamps

NCSX

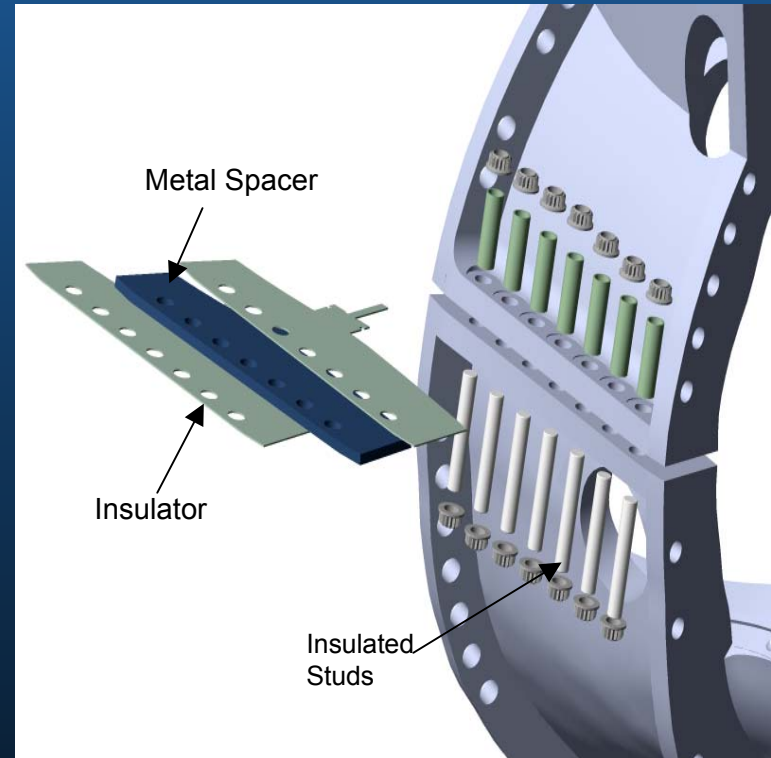
- Winding packs are clamped by discrete bracket assemblies, spaced approximately every 6-inches
- Clamp is attached by studs at base of tee and tapped holes in web of tee, shimmed to fit winding pack
- Spring washers provide compliance, allow clamp to preload winding pack to structure



# Poloidal Insulating Break

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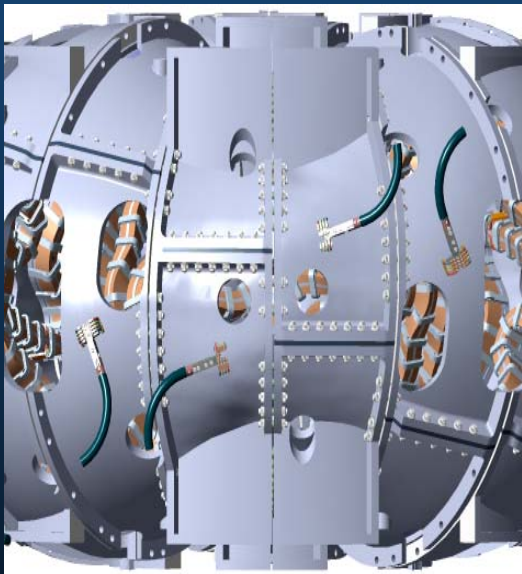
- Poloidal break is required to prevent persistent eddy currents during operation
- Fabrication approach is to saw-cut casting, insulate and bolt prior to final machining of the tee region
- Tee web connection using double insulated pin or bolt may also be required



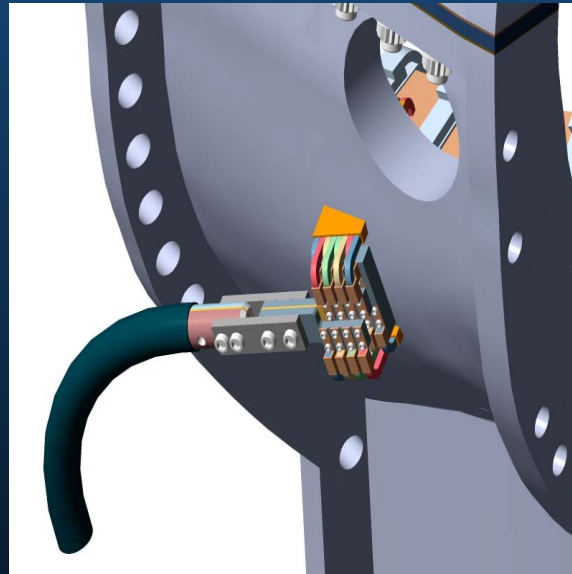
# Coil Leads

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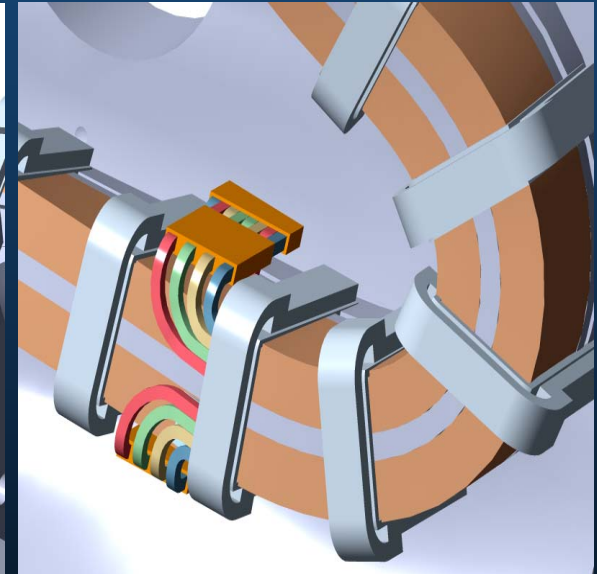
- Leads are located in “straight” outboard regions that minimize field errors
- Continuous conductors extend through shell wall to junction block on exterior surface
- Like conductors from each winding pack are connected in series to maintain current center
- A flexible co-axial cable connects block to power supply buswork outside cryostat



Up / Down Symmetry of Leads



Cable Connection at Shell Exterior



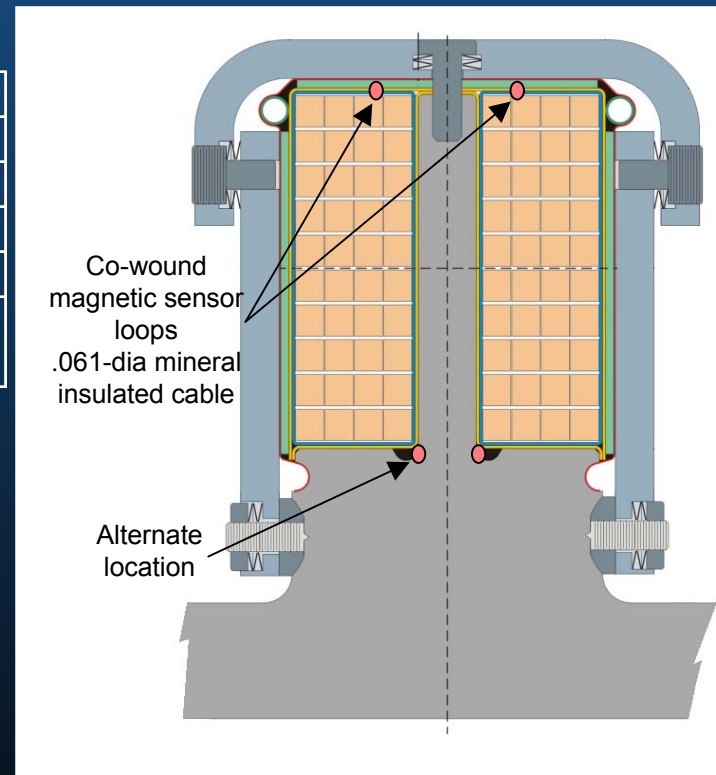
Plasma Side of Winding Pack

# Coil Instrumentation

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- Preliminary list of temperature, voltage, strain, and flow sensors has been developed
- Gages will have “back-to-back” elements that reduce EM noise during operation
- Diagnostic magnetic field sensor loops will also be co-wound with the modular coils

Modular Coil Instrumentation		
Instrumentation	Total Number	Comment
Voltage Tap	36	2 per coil
Strain Gages	72	4 per coil
Flow Sensor	36	2 per coil
RTD / Thermocouples	72	4 per coil



- **Coil services include buswork and cooling lines inside the cryostat**
- **Buswork:**
  - commercial, anti-kick cables modified for cryogenic use
  - gas feed for cooling
  - all coils (modular, PF, TF, Trim) will use the same cable design
  - prototype cable to be tested during racetrack coil testing
- **Cooling lines:**
  - consists of manifolds and lines inside cryostat
  - assume stainless steel manifolds with pigtails to each circuit
  - pigtails made from teflon hose, ala C-Mod experiment at MIT
  - assume each cooling circuit has valve and pressure gage for balancing



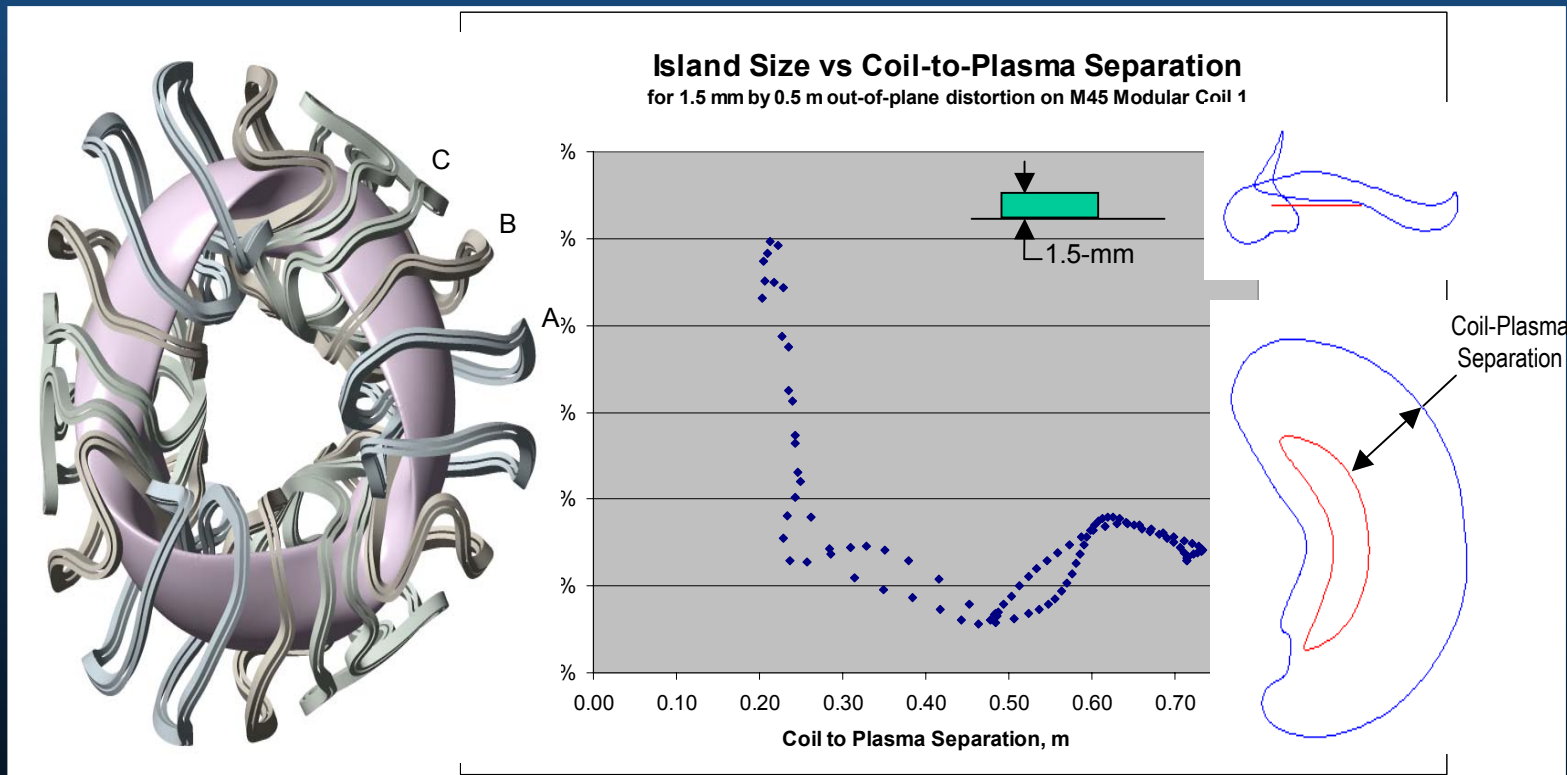
- **Preliminary design analysis has been completed for**
  - **Coil and lead field errors**
  - **Eddy currents in modular coil structure**
  - **Thermal and thermo-hydraulic response**
  - **Electromagnetic field and forces**
  - **Stress due to thermal and electromagnetic loads**
- **Structural analysis models:**
  - **Global deflection and stress in the winding forms**
  - **Nonlinear behavior of the windings due to thermal and EM loads**
  - **Deflection and stress in the clamps (racetrack coil)**
- **Detailed analysis, checking to be completed during final design**



# Coil Position Field Errors

NCSX

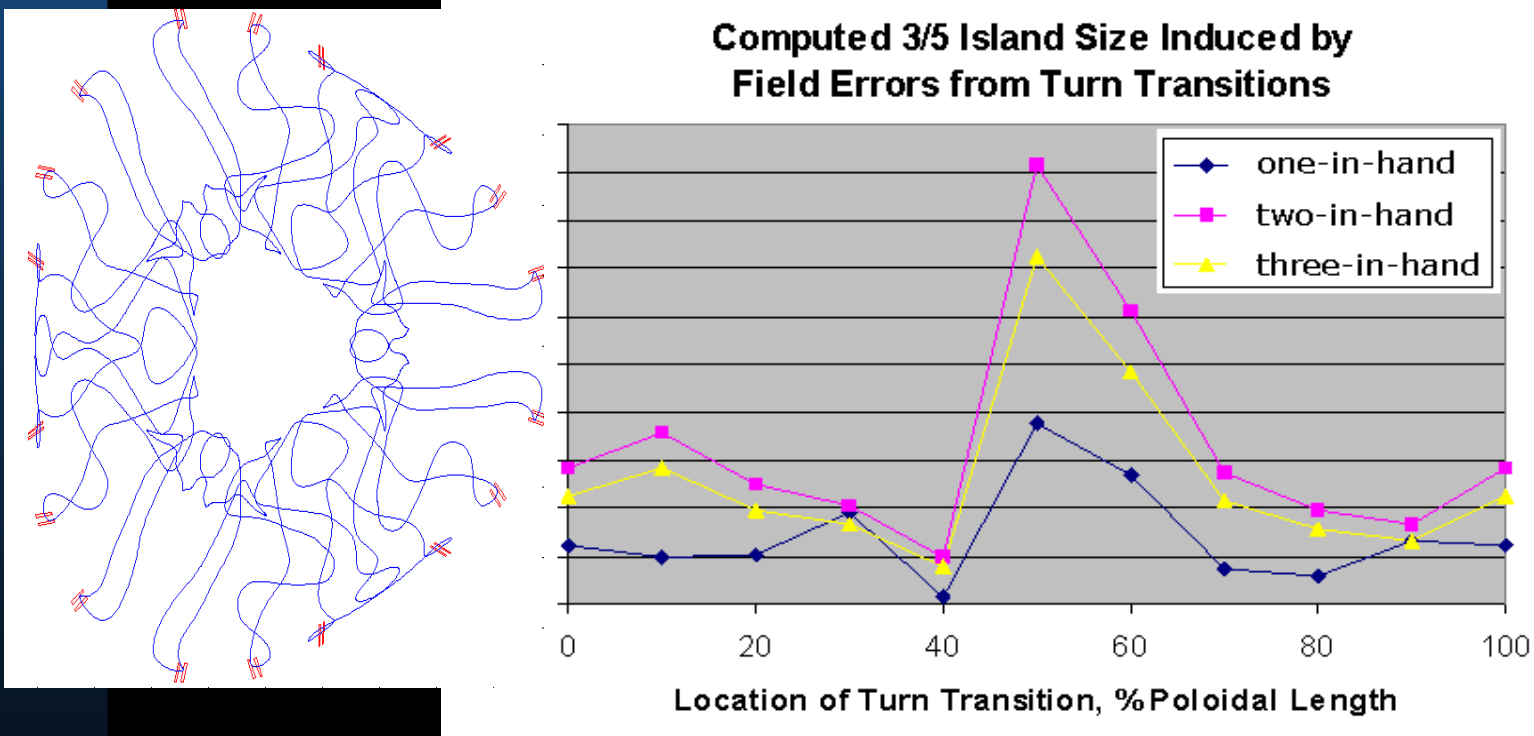
- Analysis of magnetic islands due to random errors in position of coil winding center
- Displacement error types are 1) Fourier series, 2) short wavelet, and 3) broad displacement
- Results show strong effect where coil-plasma separation <30-cm, however correctable with trim coils



# Field Error due to Leads

NCSX

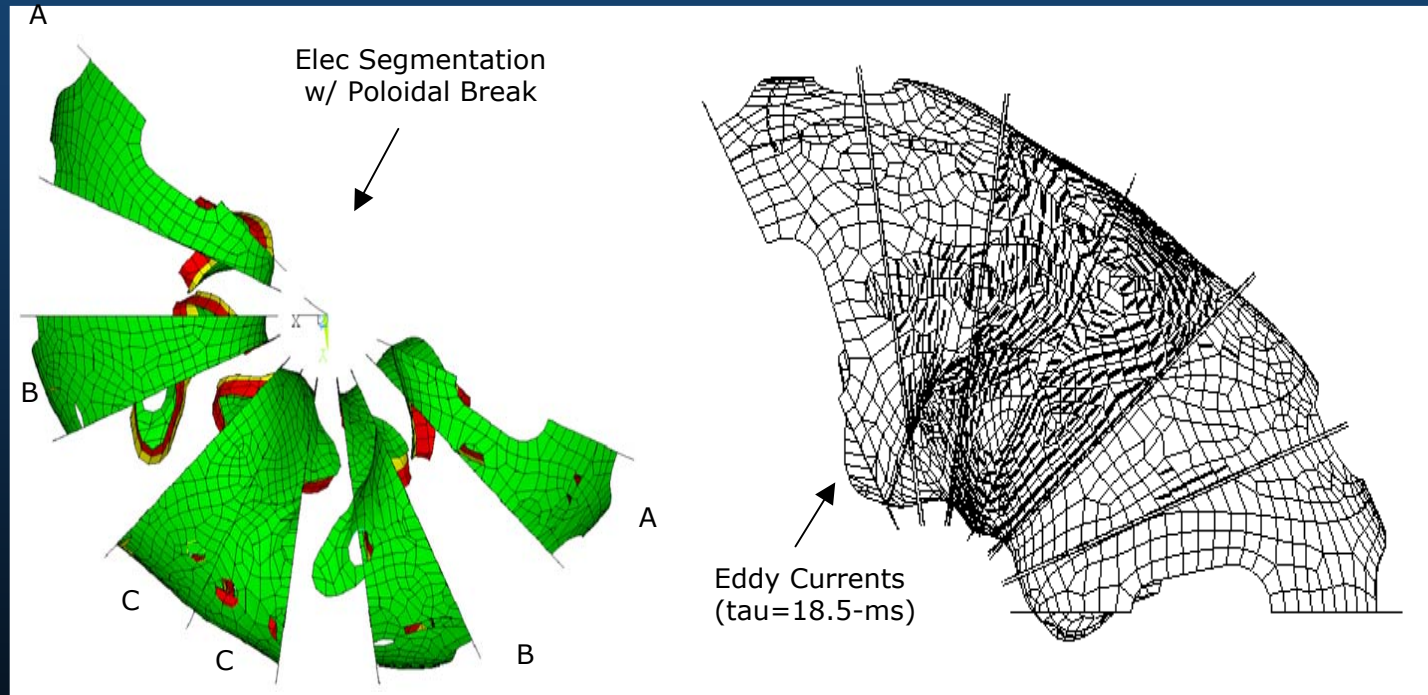
- Analysis performed with VACISLD code to determine effect of large lead currents on magnetic islands
- Poloidal location of leads was varied from outboard midplane to less practical inboard positions
- Best position appears to be 80-90% of poloidal length, near outboard midplane



# Eddy Current Evaluation

NCSX

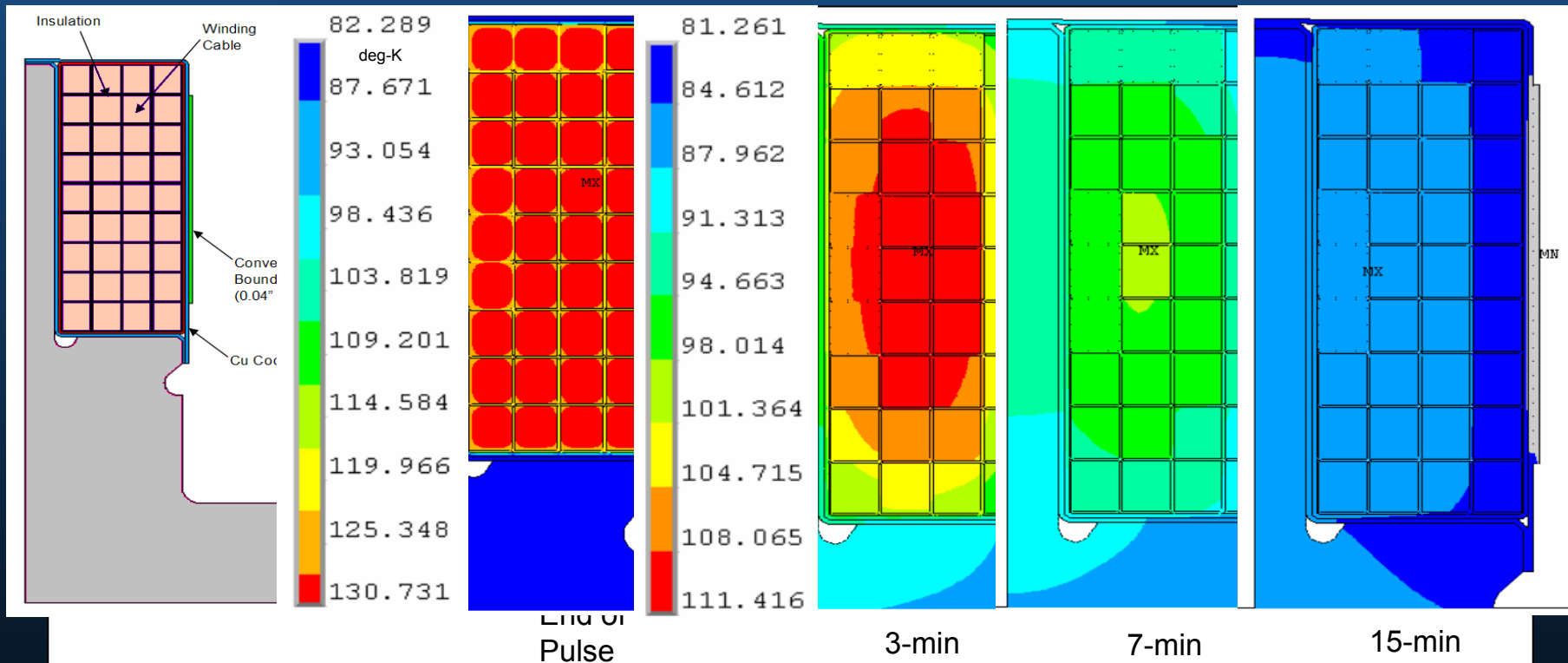
- Analysis performed with SPARK to determine eddy currents due to varying modular coil currents
- Looked at insulating break options (toroidal and poloidal), as well as segmentation of copper chill plates
- Results show longest time constant is <20-ms with one poloidal break, toroidal breaks shown
- Field period assembly joint (C-C) does not need to be insulated



# Thermal Analysis

NCSX

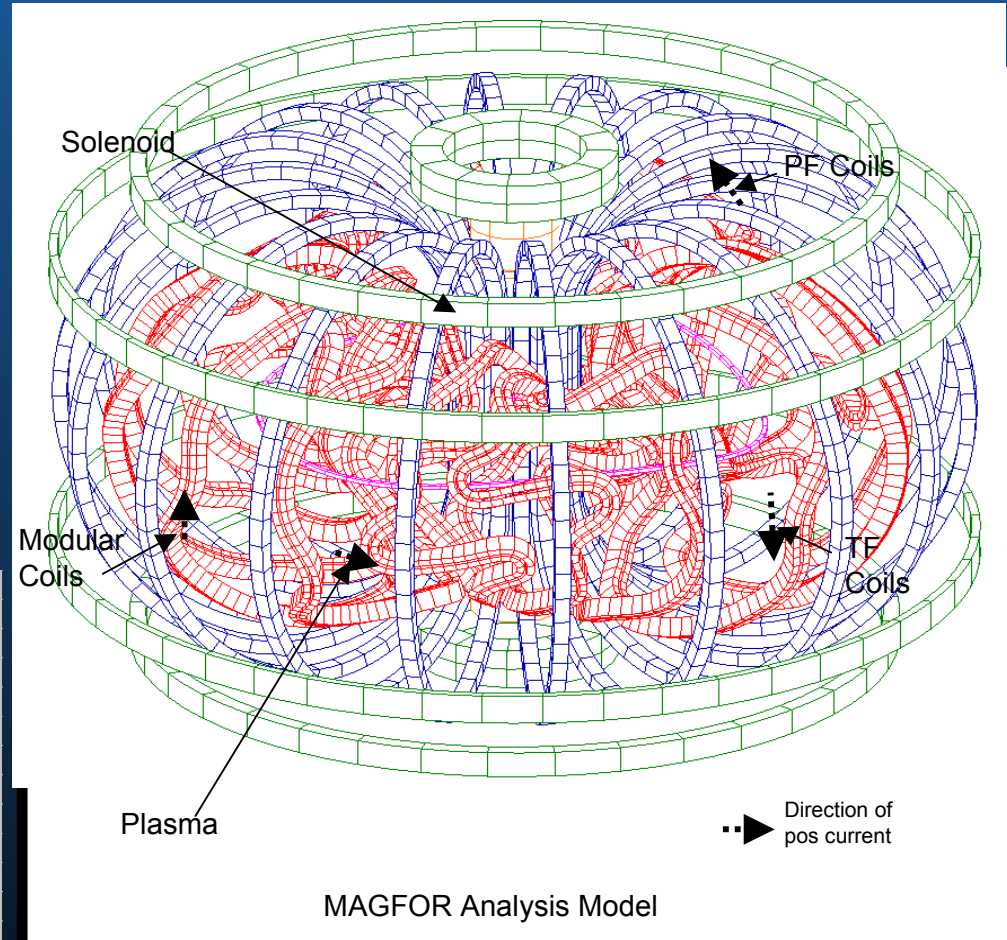
- 2D transient analysis of cooling after adiabatic heating to 130-K during pulse
- Initial temp = 85-K, cooling by conduction to trace-cooled copper chill plates, some convection
- Analysis shows cooldown in 15-min, equilibrium after ~10 cycles



# Electromagnetic Loads Analysis

NCSX

- Two independent calculations have been performed using ANSYS, MAGFOR codes
- Seven reference scenarios examined at time step with maximum modular coil current
- Scan of all possible coil currents for a more severe fault load condition is in progress



MAGFOR Analysis Model

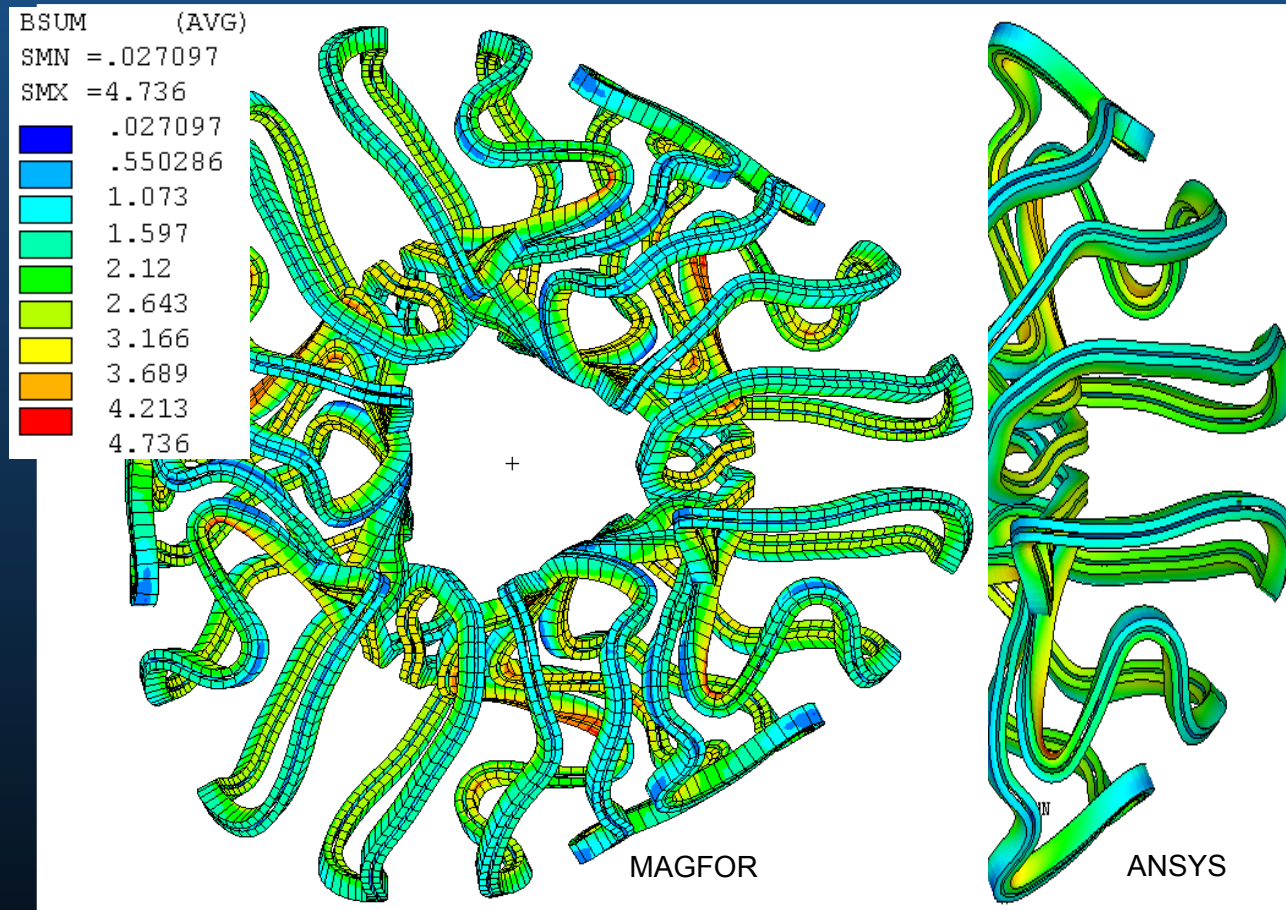
Maximum Current / Coil for Reference Scenarios (kA)

Circuit	Coil Set	Maximum Current / Coil for Reference Scenarios (kA)						
		0.5-T 1st Plasma	Field Mapping	1.7-T Ohmic	1.7-T High Beta	2-T High Beta	1.2-T L. Pulse	320-kA Ohmic
1	TF	13	13	43	45	53	30	26
2	PF1	673	0	1479	1120	1340	1191	1632
	PF2	673	0	1479	1120	1340	1191	1632
3	PF3	673	0	1286	998	1208	980	1082
4	PF4	749	734	374	416	287	313	1191
5	PF5	0	0	204	209	82	148	128
6	PF6	32	13	104	101	115	72	73
7	M1	224	224	763	763	818	539	695
8	M2	209	209	710	710	831	501	707
9	M3	188	188	638	638	731	451	621
	PLAS	35	0	120	178	210	126	321

# Magnetic Field Distribution

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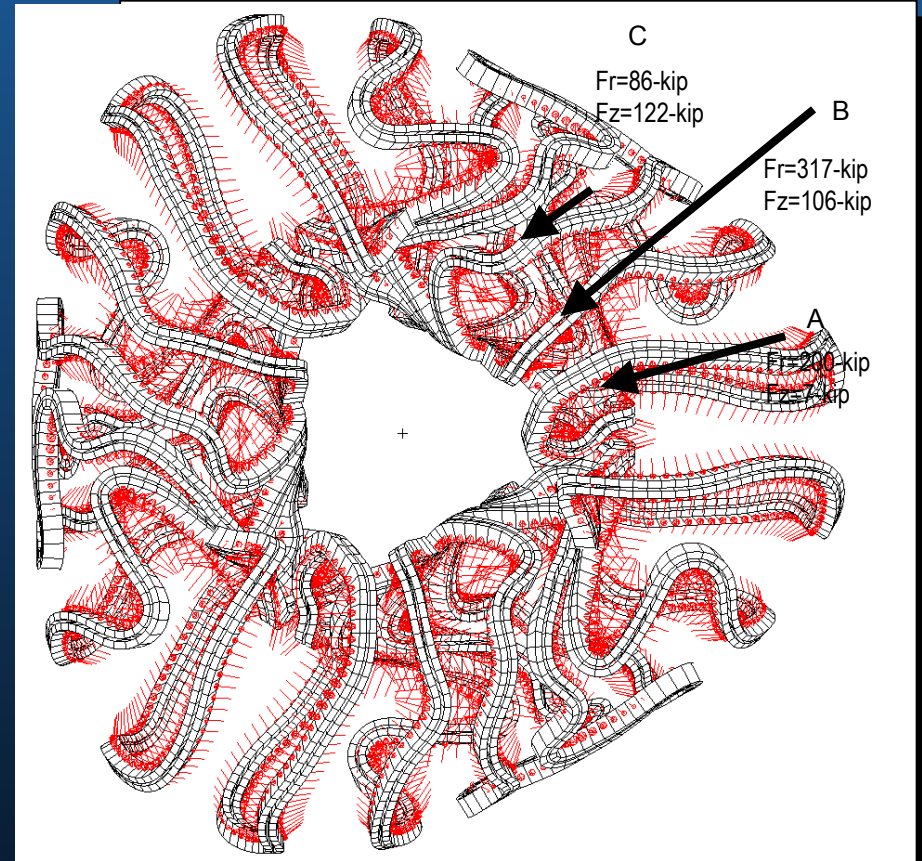
- Maximum magnetic flux density at windings is 4.7-T for 2-T reference scenario
- ANSYS, MAGFOR results differ by ~4% due to mesh and integration differences



# Force Distribution

- Force distribution indicates large centering force up to 317-kip (1.4-MN) per coil
- Net vertical load up to 122-kip (.5-MN)

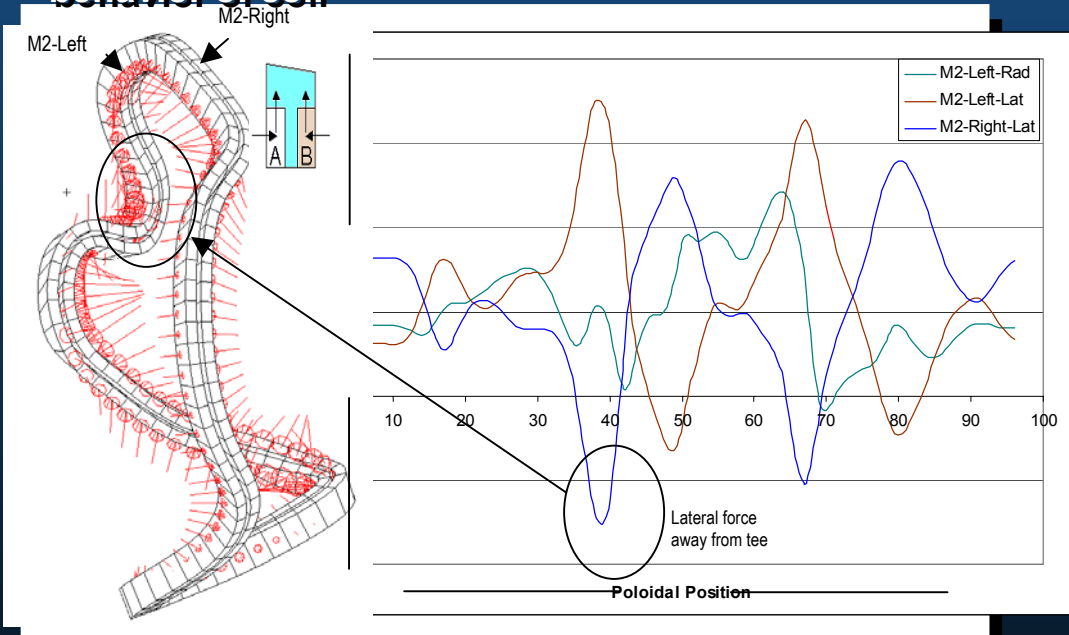
Net EM Force on Modular Coils								
Coil	Field/Force Component	0.5-T 1st Plasma	Field Mapping	1.7-T Ohmic	1.7-T High Beta	2-T High Beta	1.2-T L. Pulse	320-KA Ohmic
	Max Field at Coil (T)	1.2	0.2	4.2	4.2	4.9	2.9	4.2
M1	Net Radial Load (kip)	13	1	152	152	200	76	147
	Net Vert Load (kip)	0.5	0	9	9	7	5	7
M2	Net Radial Load (kip)	20	1	228	228	317	113	230
	Net Vert Load (kip)	7	0	84	84	106	42	79
M3	Net Radial Load (kip)	5	0	57	57	86	29	62
	Net Vert Load (kip)	8	0	95	95	122	47	89



# Force Details



- Forces have been resolved into “radial” (away from plasma) and “lateral” (toward tee web) directions
- In general, radial load is toward structure and lateral load is countered by equal force in other wp
- Sharp bends can result in lateral force away from tee; reacted by clamps and beam behavior of coil



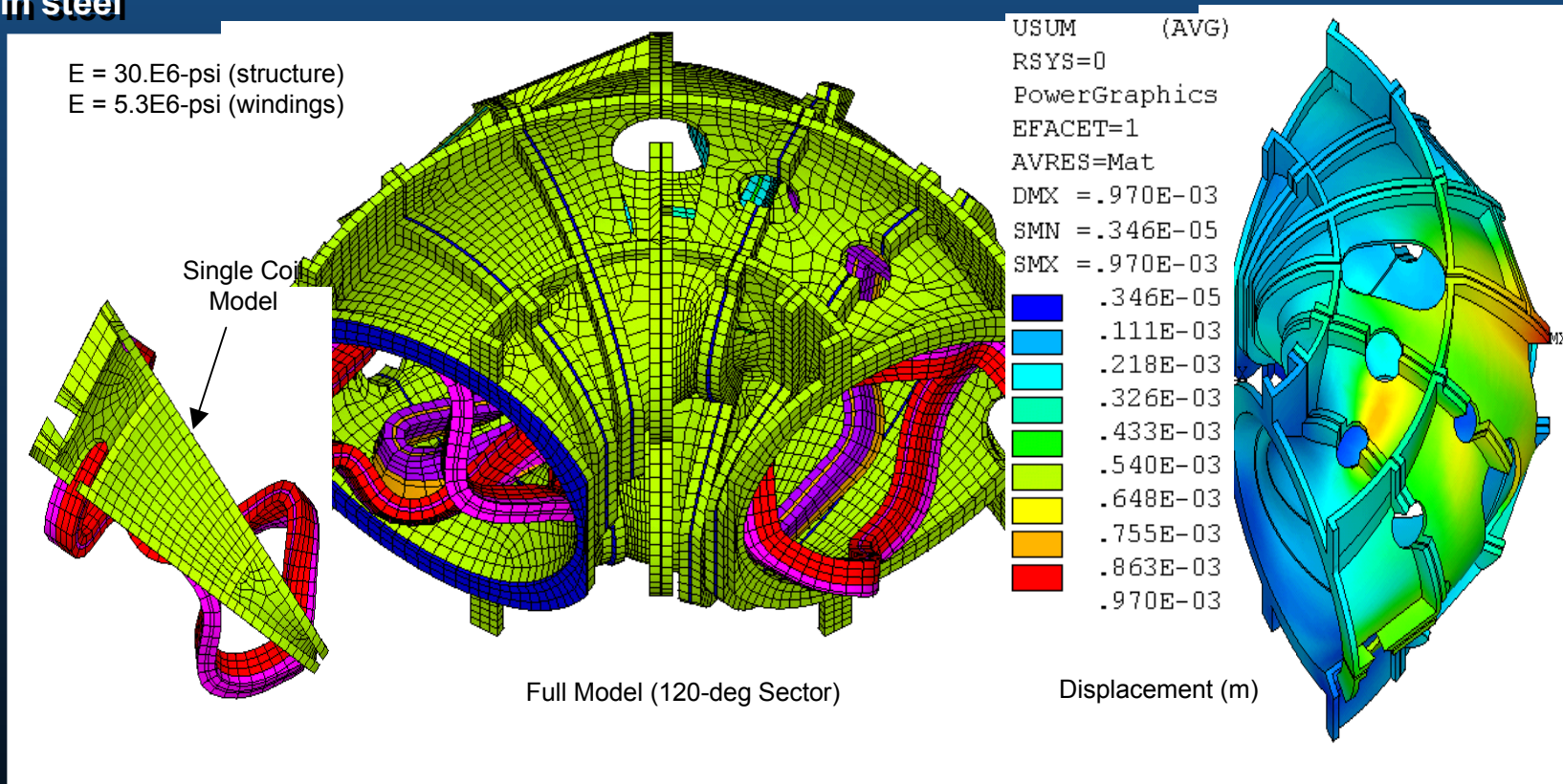
Maximum Running Load on Modular Coils (lb/in)								
Coil	Field/Force Component	0.5-T 1st Plasma	Field Mapping	1.7-T Ohmic	1.7-T High Beta	2-T High Beta	1.2-T L. Pulse	320-kA Ohmic
M1	Rad Load (lb/in)	200	8	2272	2279	2869	1134	2053
	Lat Load (lb/in)	434	17	4995	4997	5831	2490	4163
M2	Rad Load (lb/in)	351	14	4077	4076	5591	2031	4050
	Lat Load (lb/in)	430	17	4982	4983	6982	2483	5059
M3	Rad Load (lb/in)	233	9	2698	2698	3540	1344	2615
	Lat Load (lb/in)	418	17	4830	4830	6405	2407	4552



# Global Deflection and Stress

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- CDR analysis model has been updated to investigate deflection / stress in the modular coil structure
- Assumption: 2-T EM loads, coil winding is continuously supported by shell structure
- Results indicate max displacement of 0.038-in, peak Von Mises stress of 26-ksi (181-MPa) in steel

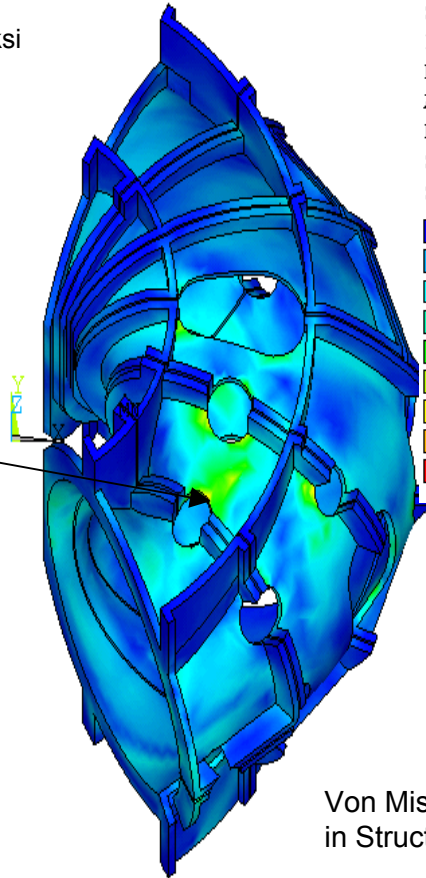
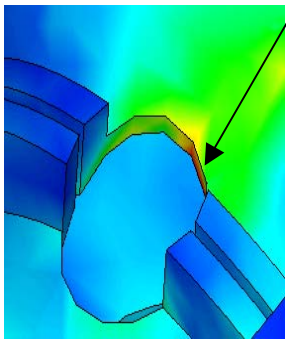


# Stress in Shell And Windings

Peak Stress = 26.3-ksi  
Avg Stress = 9-ksi

Sm = 50-ksi

Max. stress occurs at edge of opening

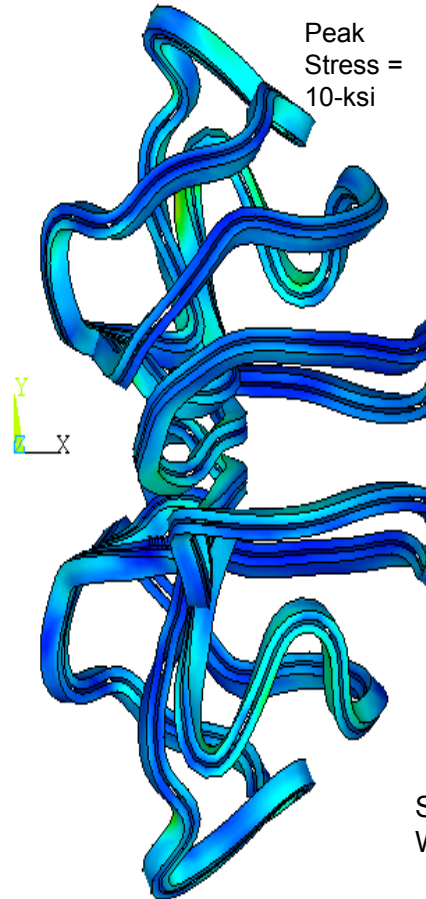


SEQV (AVG)  
PowerGraphics  
EFACET=1  
AVRES=Mat  
DMX =.970E-03  
SMN =45602  
SMX =.181E+09

45602
.201E+08
.402E+08
.603E+08
.805E+08
.101E+09
.121E+09
.141E+09
.161E+09
.181E+09

Unit of stress in pascal

Von Mises Stress in Structural Shell



Peak Stress = 10-ksi

SEQV (AVG)  
PowerGraphics  
EFACET=1  
AVRES=Mat  
DMX =.001273  
SMN =336658  
SMX =.678E+08

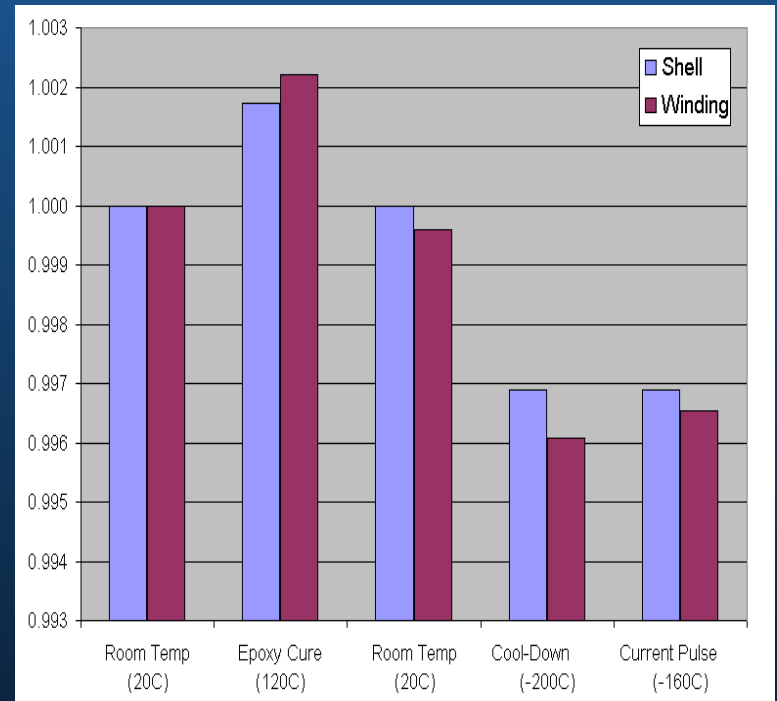
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.678E+08

Unit of stress in pascal

Stress in Windings

# Winding Thermal Stress

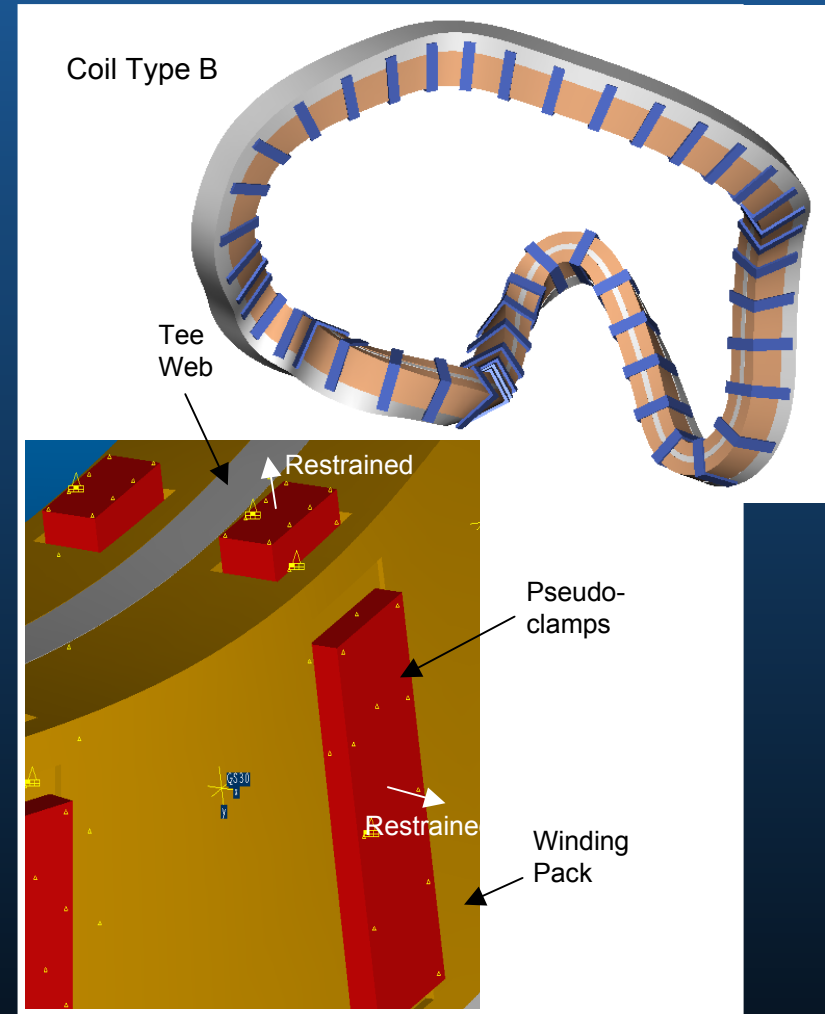
- **Relative strain between winding pack and winding form due to:**
  - **Cure shrinkage (~ 0.04%)**
  - **Cooldown to LN2 temperature (~0.04%)**
- **Winding moves away from coil form and gaps may open in localized regions**
- **Provides room for coil expansion during current pulse - 0.04% expansion relative to winding form**



# Thermal Stress Model

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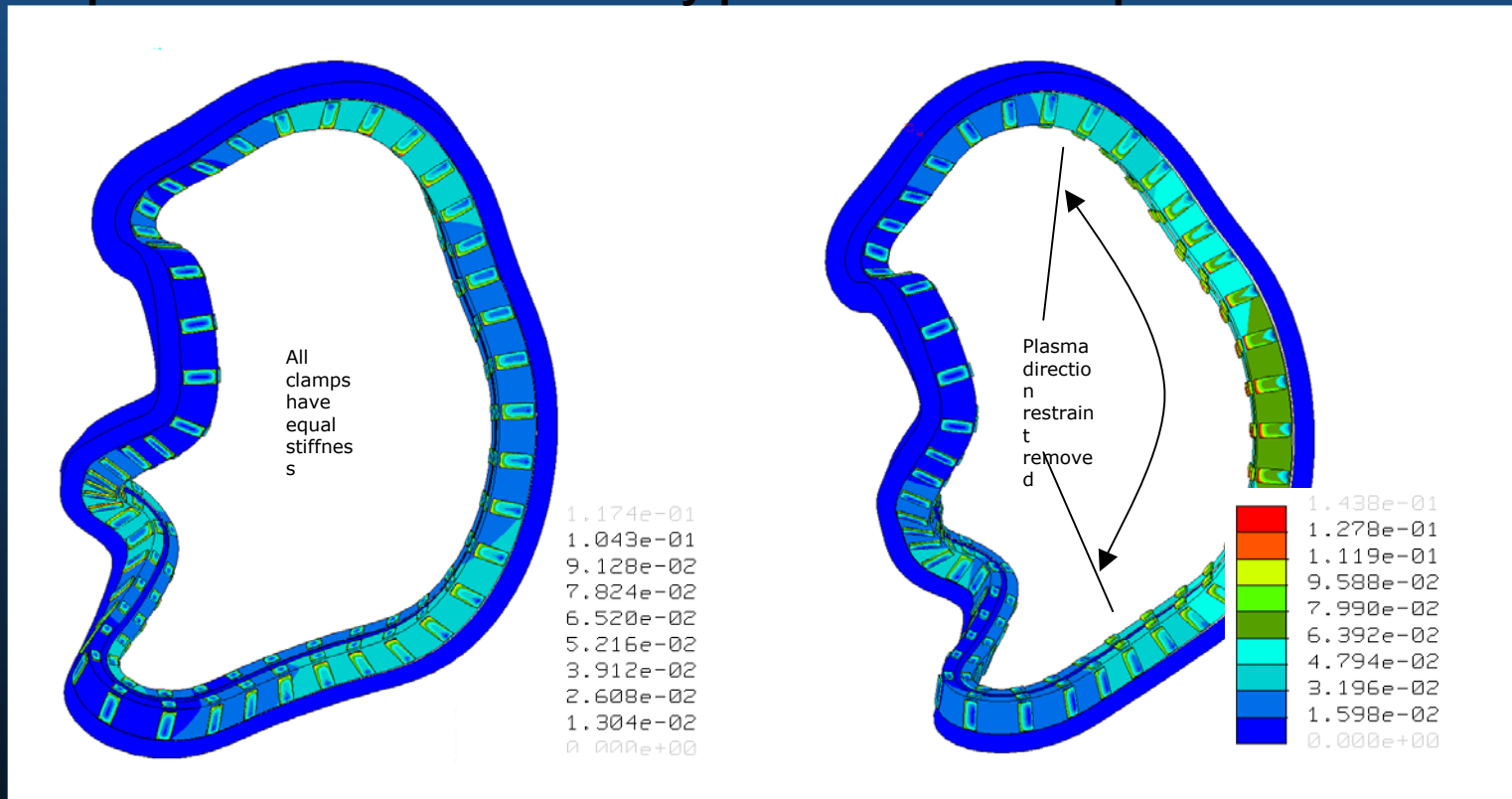
- **Non-linear model of windings on fixed tee has been developed using Pro/MECHANICA**
- **Contact surfaces between winding and tee allow winding to separate from and slide along tee**
- **Pseudo-clamps (48) are represented by low modulus material with directional restraints**
- **Properties of block simulate clamp spring force (26,000 lb/in) and preload (~1000 lb)**



# Displacement Due To Cooldown

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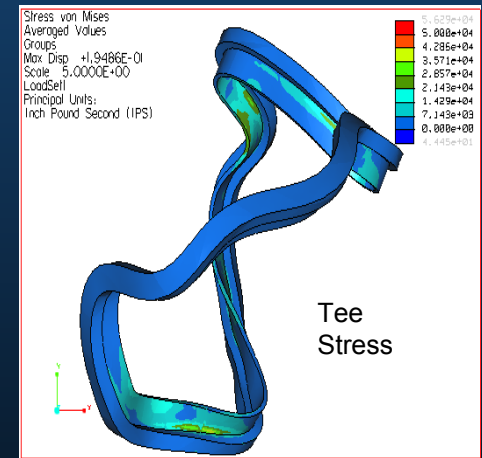
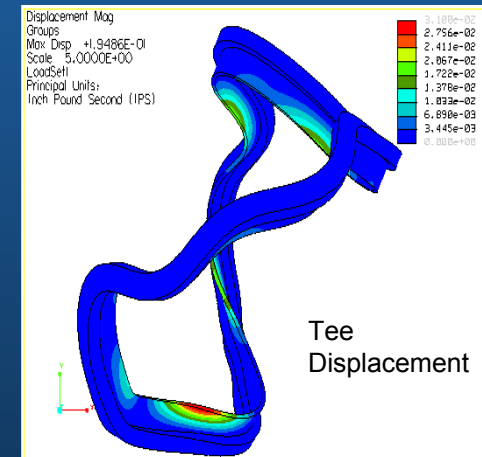
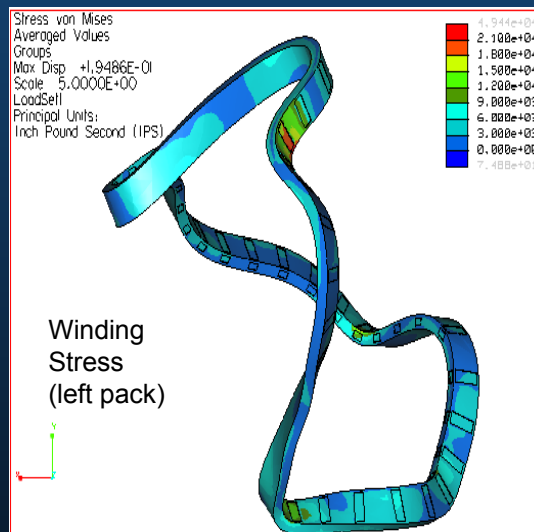
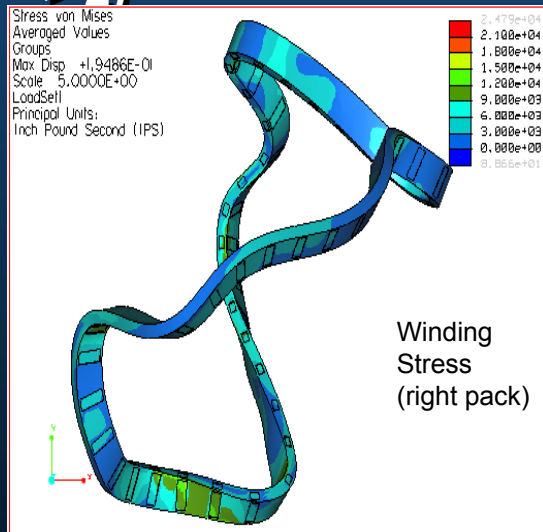
- Relative displacement due to cooldown is approximately 0.040-in (1-mm)
- Displacement can be tailored by placement of clamps



# Combined EM And Thermal Loads

NCSX

- Displacement due to max loads and cooldown is approximately 0.080-in (2-mm)
- For initial strain of 0.08%, stress ~ 16 ksi (S.F. = 1.3)
- For initial strain of 0.0%, stress ~ 10 ksi (S.F. > 2)



# Modular Coil Design/Analysis Summary

NCSX

- **Preliminary design concept meets performance requirements**
  - Accurately built 18 coil, 3 period modular coil set with integrated structure
  - 0.5-T, 0.3-s room temperature operation for first plasma, field-line mapping
  - 2-T, 1-s operation at cryogenic temperatures
  - Low permeability material, segmentation to limit eddy currents
  - Access for diagnostics, heating, vacuum pumping
  - Interface with other stellarator core components
- **Analysis shows design to be adequate for reference operating scenarios**
  - Coil cools from 40-deg temperature rise after pulse in 15-min with no ratcheting
  - Deflection of coil structure due to EM loads is <0.04-in, stress minimal (FS=2)
  - Winding stress depends on properties, initial strain due to cure and thermal shrinkage
  - Initial analysis shows stress up to 16-ksi, FS=1.3
  - Further non-linear analysis is planned during final design